# ASYMPTOTIC PROFILE FOR THE SUB-EXTREMALS OF THE SHARP SOBOLEV INEQUALITY ON THE SPHERE 

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## 0 - Introduction and statements of the results

Let $(M, g)$ be a smooth compact Riemannian $n$-manifold, $n \geq 3$, without boundary. We denote by $H_{1}^{2}(M)$ the standard Sobolev space, that is the completion of $C^{\infty}(M)$ for the norm

$$
\|u\|_{H_{1}^{2}}=\|\nabla u\|_{2}+\|u\|_{2}
$$

where $\|\cdot\|_{p}$, as in the sequel, is the $L^{p}$-norm. It follows from the Sobolev embedding theorem that $H_{1}^{2}(M) \subset L^{2^{*}}(M)$, where $2^{*}=\frac{2 n}{n-2}$ is the critical exponent. This leads to the existence of two constants $A$ and $B$ such that for any $u \in H_{1}^{2}(M)$,

$$
\begin{equation*}
\|u\|_{2^{*}}^{2} \leq A\|\nabla u\|_{2}^{2}+B\|u\|_{2}^{2} \tag{I}
\end{equation*}
$$

As usual, we define the best first constant $\alpha_{2}$ in (I) by
$\alpha_{2}=\inf \{A$ for which there exists $B$ such that $(I)$ is valid with $A$ and $B\}$
where, by $(I)$ is valid, we mean that $(I)$ holds for any $u \in H_{1}^{2}(M)$. It is now well-known, see for instance [17] for an exposition in book form, that $\alpha_{2}=K_{n}$, where $K_{n}$ is the best constant in the Euclidean Sobolev inequality. Its value has been found independently by Aubin [2] and Talenti [27] :

$$
K_{n}=\frac{4}{n(n-2)} \omega_{n}^{-\frac{2}{n}}
$$

where $\omega_{n}$ denotes the volume of the unit sphere in $\mathbb{R}^{n+1}$.
Since the work of Hebey and Vaugon [19], [20], we know that $\alpha_{2}$ is attained in $(I)$. In other words, there exists a constant $B$ such that for any $u \in H_{1}^{2}(M)$,

$$
\|u\|_{2^{*}}^{2} \leq K_{n}\|\nabla u\|_{2}^{2}+B\|u\|_{2}^{2}
$$

$$
\left(I_{o p t}\right)
$$

This inequality is optimal with respect to the first constant. One can then lower $B$ to its minimum in $\left(I_{o p t}\right)$, and thus define

$$
B_{0}(g)=\inf \left\{B \text { s.t. }\left(I_{o p t}\right) \text { is valid with } B\right\}
$$

Clearly, for any $u \in H_{1}^{2}(M)$,

$$
\|u\|_{2^{*}}^{2} \leq K_{n}\|\nabla u\|_{2}^{2}+B_{0}(g)\|u\|_{2}^{2} \quad\left(I_{g, O P T}\right)
$$

and this inequality is optimal with respect to the first and second constants. Lower and upper-bounds for $B_{0}(g)$ may be found in [17]. Following usual terminology, we say that $u_{0} \in H_{1}^{2}(M)$ is an extremal function for $\left(I_{g, O P T}\right)$ if $u_{0} \not \equiv 0$ and

$$
\left\|u_{0}\right\|_{2^{*}}^{2}=K_{n}\left\|\nabla u_{0}\right\|_{2}^{2}+B_{0}(g)\left\|u_{0}\right\|_{2}^{2}
$$

Results concerning the existence of extremal functions for $\left(I_{g, O P T}\right)$ on general compact manifolds are in Djadli-Druet [8]. In particular, it is shown there that $\left(I_{g, O P T}\right)$ possesses extremal functions if the scalar curvature of $g$ is either nonpositive or constant.

In this paper, we concentrate our attention on the case of the conformal class of the standard unit sphere. We let $\left(S^{n}, h\right)$ be the unit $n$-sphere of $\mathbb{R}^{n+1}$ with its standard metric $h$, and we let

$$
[h]=\left\{g=\varphi^{\frac{4}{n-2}} h, \varphi \in C^{\infty}(M), \varphi>0\right\}
$$

be the conformal class of $h$. Given $g \in[h]$ some conformal metric to $h$, the existence of extremal functions for $\left(I_{g, O P T}\right)$ has been studied by Hebey [16]. His result, that we recall below, should be regarded as the starting point of our paper. As in all the sequel, $S_{g}$ denotes the scalar curvature of $g$.

Theorem 0.1 ([16]) - Let $\left(S^{n}, h\right)$ be the unit $n$-sphere. If $n \geq 4$, then for any $g \in[h]$,

$$
B_{0}(g)=\frac{n-2}{4(n-1)} K_{n} \max _{S^{n}} S_{g},
$$

and there exist extremal functions for $\left(I_{g, O P T}\right)$ if and only if, up to a positive constant scale factor, $g$ and $h$ are isometric. If $n=3$, then for any $g \in[h]$,

$$
B_{0}(g) \leq \frac{1}{8} K_{3} \max _{S^{3}} S_{g},
$$

but there now exists $g \in[h]$ for which this inequality is strict. In case of equality, there exist extremal functions for $\left(I_{g, O P T}^{2}\right)$ if and only if, up to a positive constant scale factor, $g$ and $h$ are isometric.

Note that, see [17] for an exposition in book form, the extremal functions for $\left(I_{h, O P T}\right)$ are explicitly known. More precisely, if $u$ is an extremal function for $\left(I_{h, O P T}\right)$, and for instance $\int_{S^{n}} u^{2^{*}}(x) d v_{h}(x)=1$, then

$$
u(x)=\omega_{n}^{-\frac{1}{2^{*}}}\left(\beta^{2}-1\right)^{\frac{n-2}{4}}\left(\beta-\left(x_{0}, x\right)\right)^{1-\frac{n}{2}}
$$

where $\beta>1$ is some real number, $x_{0} \in S^{n}$, and $\left(x_{0}, x\right)$ denotes the scalar product in $\mathbb{R}^{n+1}$.

In what follows we assume that $n \geq 4$ and we let $g=\varphi^{\frac{4}{n-2}} h$ be some metric conformal to $h$. Given $\alpha<B_{0}(g)$, we set

$$
\lambda_{\alpha}=\inf _{u \in H_{1}^{2}\left(S^{n}\right), u \neq 0} \frac{\|\nabla u\|_{2}^{2}+\alpha K_{n}^{-1}\|u\|_{2}^{2}}{\|u\|_{2^{*}}^{2}}
$$

It follows from the definition of $B_{0}(g)$ that $\lambda_{\alpha}<K_{n}^{-1}$, while, according to Theorem 0.1,

$$
B_{0}(g)=c_{n} K_{n} \max _{S^{n}} S_{g}
$$

where $c_{n}=\frac{n-2}{4(n-1)}$. By standard variational technics, the strict inequality $\lambda_{\alpha}<K_{n}^{-1}$ leads to the existence of $z_{\alpha} \in C^{\infty}\left(S^{n}\right), z_{\alpha}>0$, such that

$$
\left\{\begin{array}{l}
\Delta_{g} z_{\alpha}+\alpha K_{n}^{-1} z_{\alpha}=\lambda_{\alpha} z_{\alpha}^{2^{*}-1} \\
\int_{S^{n}} z_{\alpha}^{2^{*}} d v_{g}=1
\end{array}\right.
$$

where $\Delta_{g}=-\operatorname{div}_{g} \nabla$. We refer to the $z_{\alpha}$ 's as sub-extremals for the sharp Sobolev inequality $\left(I_{g, O P T}\right)$. If, up to a positive constant scale factor, $g$ and $h$ are isometric, then, by a result of Gidas and Spruck [10] and Bidaut-Véron and Véron [5], $z_{\alpha}$ is constant, and hence explicitly known.

Theorem 0.2 ([10], [5]) - Let ( $\left.S^{n}, h\right)$ be the unit $n$-sphere, let $g=\varphi^{\frac{4}{n-2}} h$ be some conformal metric to $h$ such that, up to a positive constant scale factor, $g$ and $h$ are isometric, and let $\left(z_{\alpha}\right)$ be as above. Then $z_{\alpha}=\left(\alpha K_{n}^{-1} \lambda_{\alpha}^{-1}\right)^{\frac{n-2}{4}}$.

Given $g=\varphi^{\frac{4}{n-2}} h$ as above, and $n \geq 4$, we assume now that, up to any positive constant scale factor, $g$ and $h$ are not isometric. Then, according to Theorem 0.1, $\left(I_{g, O P T}\right)$ does not possess extremal functions, and one gets from standard elliptic theory that $z_{\alpha} \rightharpoonup 0$ weakly in $H_{1}^{2}\left(S^{n}\right)$ as $\alpha \rightarrow B_{0}(g)$. It thus follows that there exists $x_{0} \in S^{n}$ such that $z_{\alpha} \rightarrow 0$ in $C_{l o c}^{2}\left(S^{n} \backslash\left\{x_{0}\right\}\right)$ and $z_{\alpha}^{2^{*}} \rightarrow \delta_{x_{0}}$ in the sense of distributions. We study here the asymptotic profile of the $z_{\alpha}$ 's as $\alpha \rightarrow B_{0}(g)$, and answer a question that was asked to us by Hebey. Such studies were initiated by Atkinson-Peletier [1] and Brézis-Peletier [6] in the Euclidean context when considering the equation

$$
\Delta u=n(n-2) f(x) u^{2^{*}-1} \quad \text { in } B, u \equiv 0 \text { on } \partial B
$$

where $B$ is the unit ball of $\mathbb{R}^{n}$, and $u$ and $f$ are radially symmetrical. With arguments from ODE's theory, assuming that $f \equiv 1$, Atkinson and Peletier [1] got that

$$
\lim _{\varepsilon \rightarrow 0} \varepsilon u_{\varepsilon}(0)^{2}=\frac{4 \Gamma(n)}{(n-2) \Gamma\left(\frac{n}{2}\right)^{2}},
$$

and that, for all $x \in B \backslash\{0\}$,

$$
\lim _{\varepsilon \rightarrow 0} \varepsilon^{-\frac{1}{2}} u_{\varepsilon}(x)=\frac{\sqrt{n-2} \Gamma\left(\frac{n}{2}\right)}{2 \sqrt{\Gamma(n)}}\left(\frac{1}{|x|^{n-2}}-1\right)
$$

Brézis and Peletier [6] returned to this problem, but with arguments from PDE's theory, and they conjectured that a similar behaviour should occur in
the non radial case. This was proved to be true independently by Han [12] and Rey [25]. When $f$ is nonconstant, the problem has been considered by Hebey [15], [18], and also Robert [26] with the addition of a linear term $a(x) u$ in the equation. Similar studies have also been developed on the whole of $\mathbb{R}^{n}$. See for instance Pan-Wang [24]. Note that a key idea to get information on blow-up rate and location is to use the Pohozaev identity, respectively the Kazdan-Warner identity. This idea goes back to Brézis-Peletier [6] and Schoen [27]. See also Han [12] and Hebey [13].

For $P \in S^{n}$, and $t \in[1 ; \infty)$, we let $\Phi_{P, t}: S^{n} \rightarrow S^{n}$ be the conformal diffeomorphism defined by

$$
\Phi_{P, t}(x)=\pi_{P}^{-1}\left(t \pi_{P}(x)\right)
$$

where $\pi_{P}$ is the stereographic projection of north pole $P$. We then let $\mid$ det $d \Phi_{P, t} \mid$ be defined by

$$
\Phi_{P, t}^{*} h=\left|\operatorname{det} d \Phi_{P, t}\right|^{\frac{2}{n}} h
$$

We also denote by $G\left(x_{0}, x\right)$ the Green's function at $x_{0}$ of $\Delta_{g}+B_{0}(g) K_{n}^{-1}$. More precisely, $G\left(x_{0}, x\right)$ is the only function such that

$$
\Delta_{g} G\left(x_{0}, x\right)+B_{0}(g) K_{n}^{-1} G\left(x_{0}, x\right)=\delta_{x_{0}}
$$

in the sense of distributions. See [3] for existence and basic properties of such functions. We set

$$
\operatorname{Max}_{g}=\left\{x \in S^{n}, S_{g}(x)=\max _{y \in S^{n}} S_{g}(y)\right\}
$$

Our first result is the following :
Theorem 0.3-Let ( $\left.S^{n}, h\right)$ be the unit $n$-sphere, $n \geq 4$, let $g=\varphi^{\frac{4}{n-2}} h$ be some conformal metric to $h$ with the property that, up to any positive constant scale factor, $g$ and $h$ are not isometric, and let $\left(z_{\alpha}\right)$ be as above. There exist $x_{0} \in \operatorname{Max} S_{g}$, a sequence $\left(x_{\alpha}\right) \in S^{n}$, with the property that $x_{\alpha} \rightarrow x_{0}$ as $\alpha \rightarrow B_{0}(g)$, and a sequence $\left(t_{\alpha}\right) \in \mathbb{R}$, with the property that $t_{\alpha} \rightarrow+\infty$ as $\alpha \rightarrow B_{0}(g)$, such that

$$
t_{\alpha}^{\frac{n}{2}-1} z_{\alpha}(x) \rightarrow \varphi\left(x_{0}\right) \omega_{n}^{-\frac{1}{2^{*}}} 2^{n-2} \omega_{n-1}(n-2) G\left(x_{0}, x\right) \quad \text { in } C_{l o c}^{2}\left(S^{n} \backslash\left\{x_{0}\right\}\right)
$$

and

$$
\mid \text { det }\left.d \Phi_{x_{\alpha}, t_{\alpha}}\right|^{\frac{1}{2^{*}}} z_{\alpha} \circ \Phi_{x_{\alpha}, t_{\alpha}} \rightarrow \omega_{n}^{-\frac{1}{2^{*}}} \varphi\left(x_{0}\right)^{-1} \quad \text { in } \quad C_{l o c}^{2}\left(S^{n} \backslash\left\{-x_{0}\right\}\right)
$$

as $\alpha \rightarrow B_{0}(g)$. Moreover, $\left(\left|\operatorname{det} d \Phi_{x_{\alpha}, t_{\alpha}}\right|^{\frac{1}{2^{*}}} z_{\alpha} \circ \Phi_{x_{\alpha}, t_{\alpha}}\right)$ is uniformly bounded in $L^{\infty}\left(S^{n}\right)$.

The first part of this theorem provides us with a rather standard description of asymptotic profiles. The second part is more specific to the sphere. Our next result, Theorem 0.4 below, gives informations on the sequences $\left(t_{\alpha}\right)$ and $\left(x_{\alpha}\right)$ involved in Theorem 0.3. We let here $C_{n}$ be the dimensional constant defined by

$$
\begin{gathered}
C_{4}=\frac{1}{24} \omega_{4}^{-\frac{1}{2}}, C_{5}=\frac{3}{10 \pi} \omega_{5}^{-\frac{3}{5}}, \\
C_{6}=\frac{2}{15} \omega_{6}^{-\frac{1}{3}}, C_{n}=\frac{4}{n(n-1)(n-6)} \omega_{n}^{-\frac{2}{n}}
\end{gathered}
$$

if $n \geq 7$. We then have the following :
Theorem 0.4-Let ( $S^{n}, h$ ) be the unit $n$-sphere, $n \geq 4$, and $g=\varphi^{\frac{4}{n-2}} h$ be some conformal metric to $h$ with the property that, up to any positive constant scale factor, $g$ and $h$ are not isometric. We assume that for any $x \in \operatorname{Max}_{g}, \nabla^{2} S_{g}(x)$ is nondegenerate. For $t_{\alpha}$ as in Theorem 0.3, one then has the following :
(1) If $n=4$,

$$
\begin{aligned}
& \lim _{\alpha \rightarrow B_{0}(g)}\left(B_{0}(g)-\alpha\right) \ln t_{\alpha} \\
& =C_{4} \varphi\left(x_{0}\right)^{-1} \int_{S^{4}}\left(S_{g}\left(x_{0}\right)-S_{g}(x)\right) \varphi(x)^{-1}\left(\frac{1-\left(x_{0}, x\right)}{2}\right)^{-1} G\left(x_{0}, x\right) d v_{g}
\end{aligned}
$$

(2) If $n=5$,

$$
\begin{aligned}
& \lim _{\alpha \rightarrow B_{0}(g)}\left(B_{0}(g)-\alpha\right) t_{\alpha} \\
& =C_{5} \varphi\left(x_{0}\right)^{-\frac{1}{3}} \int_{S^{5}}\left(S_{g}\left(x_{0}\right)-S_{g}(x)\right) \varphi(x)^{-1}\left(\frac{1-\left(x_{0}, x\right)}{2}\right)^{-\frac{3}{2}} G\left(x_{0}, x\right) d v_{g}
\end{aligned}
$$

(3) If $n=6$,

$$
\lim _{\alpha \rightarrow B_{0}(g)}\left(B_{0}(g)-\alpha\right) \frac{t_{\alpha}^{2}}{\ln t_{\alpha}}=C_{6} \varphi\left(x_{0}\right) \Delta_{g} S_{g}\left(x_{0}\right)
$$

(4) If $n \geq 7$,

$$
\lim _{\alpha \rightarrow B_{0}(g)}\left(B_{0}(g)-\alpha\right) t_{\alpha}^{2}=C_{n} \varphi\left(x_{0}\right)^{2^{*}-2} \Delta_{g} S_{g}\left(x_{0}\right)
$$

Moreover, at least when $n \geq 7$, and for $x_{\alpha}$ and $x_{0}$ as in Theorem 0.3, one may take $x_{\alpha}=x_{0}$ for any $\alpha$.

By a well-known result of Obata [23], if $g \in[h]$ and $S_{g}$ is constant, then, up to a positive constant scale factor, $g$ and $h$ are isometric. Given $g \in[h]$, the limits involved in points (1) and (2) of Theorem 0.4 are then nonnegative, and null if and only if, up to a positive constant scale factor, $g$ and $h$ are isometric. Under the assumption that $\nabla^{2} S_{g}(x)$ is definite negative for any $x \in \operatorname{Max}_{g}$, the limits involved in (3) and (4) are also positive.

In our last result we restrict ourselves to a particular case where we can drop the assumption of nondegeneracy we made on $S_{g}$ in Theorem 0.4, and where we get a complete description of the asymptotic profile of the sub-extremals, hence of the sequences $\left(x_{\alpha}\right)$ and $\left(t_{\alpha}\right)$ involved in Theorem 0.3 . More precisely, we assume now that $\varphi$ is radially symmetrical with respect to some point $x_{0} \in S^{n}$ and that $S_{g}$, which is therefore also radially symmetrical with respect to $x_{0}$, achieves its maximum at $x_{0}$. Under such assumptions, one easily checks that we can choose the sub-extremals $z_{\alpha}$ to be radially symmetrical with respect to $x_{0}$, and to blow-up at $x_{0}$ (see section 4 below for more details on such an assertion). We let $p \in \mathbb{N}^{*}$ be such that

$$
\Delta_{g}^{i} S_{g}\left(x_{0}\right)=0 \text { for any } 1 \leq i<p, \text { and } \Delta_{g}^{p} S_{g}\left(x_{0}\right) \neq 0
$$

with the convention that $p=+\infty$ if $\Delta_{g}^{i} S_{g}\left(x_{0}\right)=0$ for any $i \in \mathbb{N}^{*}$, where

$$
\Delta_{g}^{i}=\Delta_{g} \circ \ldots \circ \Delta_{g} \quad(i \text { times })
$$

We let also

$$
\begin{gathered}
D_{1}(n, p)=\frac{(p+1) 4^{p}}{n(n-1)(2 p)!} \omega_{n}^{-\frac{2}{n}}\left(\Pi_{k=0 \ldots p-1} \frac{2 k+1}{n-6-2 k}\right) \\
D_{2}(n)=\frac{2^{n-5}(n-2) \omega_{n}^{-\frac{2}{n}}}{(n-4)!n(n-1)}\left(\prod_{k=0}^{\frac{n-6}{2}} \frac{2 k+1}{n+2 k}\right)\left(\int_{0}^{\infty} \frac{r^{n-1}}{\left(1+r^{2}\right)^{n-2}} d r\right)^{-1} \\
D_{3}(n)=\frac{(n-2)^{2}}{8 n(n-1)} \omega_{n}^{-\frac{2}{n}} \omega_{n-1}\left(\int_{0}^{\infty} \frac{r^{n-1}}{\left(1+r^{2}\right)^{n-2}} d r\right)^{-1}
\end{gathered}
$$

Our last result is then as follows :

Theorem 0.5-Let $\left(S^{n}, h\right)$ be the unit $n$-sphere, $n \geq 4$, and let $g=\varphi^{\frac{4}{n-2}} h$ be some conformal metric to $h$ with the property that, up to any positive constant scale factor, $g$ and $h$ are not isometric. We assume that $\varphi$ is radially symmetrical with respect to some $x_{0} \in S^{n}$, that $S_{g}$ achieves its maximum at $x_{0}$, and we choose the sub-extremals $z_{\alpha}$ to be radially symmetrical with respect to $x_{0}$, and to blow-up at $x_{0}$. Then Theorem 0.3 holds for $z_{\alpha}$ with $x_{\alpha}=x_{0}$ for every $\alpha$. Moreover, $t_{\alpha}$ verifies :
(1) If $n=4$,

$$
\begin{aligned}
& \lim _{\alpha \rightarrow B_{0}(g)}\left(B_{0}(g)-\alpha\right) \ln t_{\alpha}=\frac{1}{24} \omega_{4}^{-\frac{1}{2}} \varphi\left(x_{0}\right)^{-1} \\
& \quad \times \int_{S^{4}}\left(S_{g}\left(x_{0}\right)-S_{g}(x)\right) \varphi(x)^{-1}\left(\frac{1-\left(x_{0}, x\right)}{2}\right)^{-1} G\left(x_{0}, x\right) d v_{g}
\end{aligned}
$$

(2) If $n=5$,

$$
\begin{aligned}
& \lim _{\alpha \rightarrow B_{0}(g)}\left(B_{0}(g)-\alpha\right) t_{\alpha}=\frac{3}{10 \pi} \omega_{5}^{-\frac{3}{5}} \varphi\left(x_{0}\right)^{-\frac{1}{3}} \\
& \quad \times \int_{S^{5}}\left(S_{g}\left(x_{0}\right)-S_{g}(x)\right) \varphi(x)^{-1}\left(\frac{1-\left(x_{0}, x\right)}{2}\right)^{-\frac{3}{2}} G\left(x_{0}, x\right) d v_{g}
\end{aligned}
$$

(3) If $n \geq 6$, and

$$
\text { (3a) } 2 p<n-4 \text {, }
$$

$$
\lim _{\alpha \rightarrow B_{0}(g)}\left(B_{0}(g)-\alpha\right) t_{\alpha}^{2 p}=-D_{1}(n, p) \varphi\left(x_{0}\right)^{p\left(2^{*}-2\right)}\left(-\Delta_{g}\right)^{p} S_{g}\left(x_{0}\right)
$$

(3b) $2 p=n-4$,

$$
\lim _{\alpha \rightarrow B_{0}(g)}\left(B_{0}(g)-\alpha\right) \frac{t_{\alpha}^{n-4}}{\ln t_{\alpha}}=-D_{2}(n) \varphi\left(x_{0}\right)^{\frac{2(n-4)}{n-2}}\left(-\Delta_{g}\right)^{\frac{n}{2}-2} S_{g}\left(x_{0}\right)
$$

(3c) $2 p>n-4$,

$$
\begin{aligned}
\lim _{\alpha \rightarrow B_{0}(g)} & \left(B_{0}(g)-\alpha\right) t_{\alpha}^{n-4}=D_{3}(n) \varphi\left(x_{0}\right)^{\frac{n-6}{n-2}} \\
& \times \int_{S^{n}}\left(S_{g}\left(x_{0}\right)-S_{g}(x)\right) \varphi(x)^{-1}\left(\frac{1-\left(x_{0}, x\right)}{2}\right)^{1-\frac{n}{2}} G\left(x_{0}, x\right) d v_{g}
\end{aligned}
$$

where $p, D_{1}(n, p), D_{2}(n)$, and $D_{3}(n)$ are as above.

As in Theorem 0.4, the limits in Theorem 0.5 are always positive (since $S_{g}$ is nonconstant by Obata's theorem [23]). Clearly, in the radial case, Theorem 0.5 provides us with a complete description of the asymptotic profile of the sub-extremals.

## 1 - Proof of Theorem 0.3

As a starting point, we list some useful formulae regarding the $\Phi_{P, t}$ 's introduced above. Let $P \in S^{n}$ and $t \geq 1$. As easily seen, see for instance [17], p.130-131, one has that

$$
\begin{equation*}
\text { |det }\left.d \Phi_{P, t}\right|^{\frac{2}{n}}(x)=4 t^{2}\left[\left(1+t^{2}\right)+\left(t^{2}-1\right)(P, x)\right]^{-2} \tag{1.1}
\end{equation*}
$$

where $(P, x)$ denotes the scalar product in $\mathbb{R}^{n+1}$, as in the rest of this paper. As $t \rightarrow+\infty, \Phi_{P, t}(x) \rightarrow P$ for all $x \neq-P$. This is easily seen on the following: for any $x \in S^{n}$,

$$
\begin{equation*}
\left(\Phi_{P, t}(x), P\right)=1-2 \frac{1-(x, P)}{t^{2}(1+(x, P))+1-(x, P)} \tag{1.2}
\end{equation*}
$$

Given $Q \in S^{n}$, we let $\pi_{Q}$ be the stereographic projection of north pole $Q$. Easy computations lead to the following : for any $x \in \mathbb{R}^{n}$,

$$
\begin{equation*}
\left(P, \pi_{-P}^{-1}(x)\right)=\frac{1-|x|^{2}}{1+|x|^{2}} \tag{1.3}
\end{equation*}
$$

and

$$
\begin{equation*}
\left|\operatorname{det} d \Phi_{P, t}\right|^{\frac{2}{n}}\left(\pi_{-P}^{-1}(x)\right)=t^{2}\left(1+|x|^{2}\right)^{2}\left(t^{2}+|x|^{2}\right)^{-2} \tag{1.4}
\end{equation*}
$$

At last, for any $f \in C^{0}\left(S^{n}\right)$ and any $x \in \mathbb{R}^{n}$, we have

$$
\begin{equation*}
f \circ \Phi_{P, t} \circ \pi_{-P}^{-1}(x)=f \circ \pi_{-P}^{-1}\left(\frac{x}{t}\right) \tag{1.5}
\end{equation*}
$$

Now, we go on with the proof of Theorem 0.3.

## 1.1 - The concentration phenomenon

We let $z_{\alpha}$ be as in the introduction, $\alpha<B_{0}(g)$. As already mentioned, $z_{\alpha} \rightharpoonup 0$ weakly in $H_{1}^{2}\left(S^{n}\right)$. Another easy claim is that

$$
\lim _{\alpha \rightarrow B_{0}(g)} \lambda_{\alpha}=K_{n}^{-1}
$$

We list in this subsection results on the concentration phenomenon that the $z_{\alpha}$ 's develop. These results have already been proved in [8] (see also Druet [9]). We therefore omit giving too many details.

As a starting claim, there exists a unique point $x_{0}$ in $S^{n}$ such that, after passing to a subsequence,

$$
\lim _{\alpha \rightarrow B_{0}(g)} \int_{B\left(x_{0}, \delta\right)} z_{\alpha}^{2^{*}} d v_{g}=1 \quad \text { for any } \delta>0
$$

and

$$
\begin{equation*}
\lim _{\alpha \rightarrow B_{0}(g)} z_{\alpha}=0 \quad \text { in } C_{l o c}^{2}\left(S^{n} \backslash\left\{x_{0}\right\}\right) \tag{1.6}
\end{equation*}
$$

The $L^{2^{*}}$-mass of $\left(z_{\alpha}\right)$ therefore concentrates around $x_{0}$. We set $u_{\alpha}=z_{\alpha} \varphi$. As easily checked, $u_{\alpha}$ is such that

$$
\begin{align*}
& L_{h} u_{\alpha}+\left(\alpha K_{n}^{-1}-c_{n} S_{g}\right) \varphi^{2^{*}-2} u_{\alpha}=\lambda_{\alpha} u_{\alpha}^{2^{*}-1} \\
& \int_{S^{n}} u_{\alpha}^{2^{*}} d v_{h}=1
\end{align*}
$$

where $L_{h}=\Delta_{h}+\frac{n(n-2)}{4}$ is the conformal Laplacian for the metric $h$. We let also $x_{\alpha} \in S^{n}$ be a point where $u_{\alpha}$ is maximum. Clearly, $u_{\alpha}\left(x_{\alpha}\right) \rightarrow+\infty$ and $x_{\alpha} \rightarrow x_{0}$ as $\alpha \rightarrow B_{0}(g)$. We let

$$
\begin{equation*}
t_{\alpha}=\omega_{n}^{\frac{1}{n}} u_{\alpha}\left(x_{\alpha}\right)^{\frac{2}{n-2}} \tag{1.7}
\end{equation*}
$$

and set

$$
v_{\alpha}=u_{\alpha} \circ \Phi_{\alpha}\left|\operatorname{det} d \Phi_{\alpha}\right|^{\frac{1}{2^{*}}}
$$

where $\Phi_{\alpha}=\Phi_{x_{\alpha}, t_{\alpha}}$. As easily checked,

$$
\begin{align*}
& L_{h} v_{\alpha}+\left(\alpha K_{n}^{-1}-c_{n} S_{g} \circ \Phi_{\alpha}\right)\left(\varphi \circ \Phi_{\alpha}\right)^{2^{*}-2}\left|\operatorname{det} d \Phi_{\alpha}\right|^{\frac{2}{n}} v_{\alpha}=\lambda_{\alpha} v_{\alpha}^{2^{*}-1} \\
& \int_{S^{n}} v_{\alpha}^{2^{*}} d v_{h}=1
\end{align*}
$$

For $\pi_{-x_{\alpha}}$ the stereographic projection of north pole $-x_{\alpha}$, we set

$$
\tilde{S}_{\alpha}=S_{g} \circ \pi_{-x_{\alpha}}^{-1}, \quad \tilde{\varphi}_{\alpha}=\varphi \circ \pi_{-x_{\alpha}}^{-1}, \quad \tilde{v}_{\alpha}=v_{\alpha} \circ \pi_{-x_{\alpha}}^{-1}
$$

Since

$$
\left(\pi_{-x_{\alpha}}^{-1}\right)^{*} h=\psi^{\frac{4}{n-2}} \xi \quad \text { and } \quad \psi(x)=\left(\frac{2}{1+|x|^{2}}\right)^{\frac{n}{2}-1}
$$

where $\xi$ is the Euclidean metric, we get with (1.4) and (1.5) that

$$
\begin{aligned}
\Delta_{\xi}\left(\tilde{v}_{\alpha} \psi\right)= & \lambda_{\alpha}\left(\tilde{v}_{\alpha} \psi\right)^{2^{*}-1} \\
& +4\left(c_{n} \tilde{S}_{\alpha}\left(\frac{x}{t_{\alpha}}\right)-\alpha K_{n}^{-1}\right) \tilde{\varphi}_{\alpha}\left(\frac{x}{t_{\alpha}}\right)^{2^{*}-2} t_{\alpha}^{-2}\left(1+\frac{|x|^{2}}{t_{\alpha}^{2}}\right)^{-2} \tilde{v}_{\alpha} \psi
\end{aligned}
$$

Moreover, one easily checks with (1.7) and (1.4) that

$$
\left\|\tilde{v}_{\alpha} \psi\right\|_{\infty}=\tilde{v}_{\alpha}(0) \psi(0)=2^{\frac{n}{2}-1} \omega_{n}^{-\frac{1}{2^{*}}}
$$

Independently, it is clear that $\left(\tilde{v}_{\alpha} \psi\right)$ is bounded in $H_{1}^{2}\left(\mathbb{R}^{n}\right)$ and in $L^{\infty}\left(\mathbb{R}^{n}\right)$. By standard elliptic theory (see [11], theorem 8.17), $\left(\tilde{v}_{\alpha} \psi\right)$ is then uniformly continuous. It hence follows from Ascoli's theorem that $\tilde{v}_{\alpha} \psi \rightarrow \tilde{v}$ in $C_{l o c}^{0}\left(\mathbb{R}^{n}\right)$ as $\alpha \rightarrow B_{0}(g)$, where

$$
\|\tilde{v}\|_{\infty}=\tilde{v}(0)=2^{\frac{n}{2}-1} \omega_{n}^{-\frac{1}{2^{*}}}
$$

and $\tilde{v}$ is such that

$$
\Delta_{\xi} \tilde{v}=K_{n}^{-1} \tilde{v}^{2^{*}-1}
$$

By a well known result of Caffarelli, Gidas and Spruck [7],

$$
\tilde{v}=\omega_{n}^{-\frac{1}{2^{*}}} \psi(x)
$$

Thus, up to standard elliptic theory,

$$
\begin{equation*}
\lim _{\alpha \rightarrow B_{0}(g)} \tilde{v}_{\alpha}=\omega_{n}^{-\frac{1}{2^{*}}} \quad \text { in } C_{l o c}^{2}\left(\mathbb{R}^{n}\right) \tag{1.8}
\end{equation*}
$$

This convergence result gives informations on the speed of concentration of the $L^{2^{*}}$-norm of $\left(z_{\alpha}\right)$. Indeed, for any $R>0$,

$$
\begin{align*}
\int_{B\left(x_{\alpha}, R t_{\alpha}^{-1}\right)} z_{\alpha}^{2^{*}} d v_{g} & =\int_{B\left(x_{\alpha}, R t_{\alpha}^{-1}\right)} u_{\alpha}^{2^{*}} d v_{h} \\
& =\int_{B\left(x_{\alpha}, \pi-\varepsilon^{\prime}(R)\right)} v_{\alpha}^{2^{*}} d v_{h}  \tag{1.3}\\
& \rightarrow 1-\varepsilon(R) \quad \text { as } \alpha \rightarrow B_{0}(g) \tag{1.8}
\end{align*}
$$

where $\varepsilon(R), \varepsilon^{\prime}(R)$ go to 0 as $R \rightarrow+\infty$. In other words,

$$
\begin{equation*}
\lim _{R \rightarrow+\infty} \lim _{\alpha \rightarrow B_{0}(g)} \int_{B\left(x_{\alpha}, R t_{\alpha}^{-1}\right)} z_{\alpha}^{2^{*}} d v_{g}=1 \tag{1.9}
\end{equation*}
$$

As it was shown in [8], see also [9], this integral estimate leads to pointwise estimates: there exists some positive constant $C$ such that

$$
\begin{equation*}
d_{g}\left(x_{\alpha}, x\right)^{\frac{n}{2}-1} z_{\alpha}(x) \leq C \quad \text { for any } \alpha, \text { and any } x \in S^{n} \tag{1.10}
\end{equation*}
$$

and one also has that

$$
\begin{equation*}
\lim _{R \rightarrow+\infty} \lim _{\alpha \rightarrow B_{0}(g)} \sup _{x \in S^{n} \backslash B\left(x_{\alpha}, R t_{\alpha}^{-1}\right)} d_{g}\left(x_{\alpha}, x\right)^{\frac{n}{2}-1} z_{\alpha}(x)=0 \tag{1.11}
\end{equation*}
$$

We refer the reader to [8] for details on these assertions. Moreover, it was also proved there that in such a situation, if there are no extremal functions for $\left(I_{g, O P T}\right)$ (which is the case here), then

$$
B_{0}(g) \leq c_{n} K_{n} S_{g}\left(x_{0}\right)
$$

where $x_{0}$ is the point of concentration of $\left(z_{\alpha}\right)$. Thus $x_{0} \in \operatorname{Max} S_{g}$. Together with (1.8), this proves the second part of Theorem 0.3 :

$$
\lim _{\alpha \rightarrow B_{0}(g)} z_{\alpha} \circ \Phi_{\alpha}\left|\operatorname{det} d \Phi_{\alpha}\right|^{\frac{1}{2^{*}}}=\varphi\left(x_{0}\right)^{-1} \omega_{n}^{-\frac{1}{2^{*}}} \quad \text { in } C_{l o c}^{2}\left(S^{n} \backslash\left\{-x_{0}\right\}\right)
$$

We provide in the next subsection a stronger pointwise estimate than (1.10) and (1.11). This will allow us to conclude the proof of Theorem 0.3.

## 1.2-A fundamental estimate

We prove here the following estimate : there exists $C>0$ such that for any $\alpha<B_{0}(g)$, and any $x \in S^{n}$,

$$
\begin{equation*}
d_{g}\left(x, x_{\alpha}\right)^{n-2} z_{\alpha}\left(x_{\alpha}\right) z_{\alpha}(x) \leq C \tag{1.12}
\end{equation*}
$$

Similar estimates are in Han [12], Hebey-Vaugon [19], Li [22], Schoen-Zhang [28]. We divide the proof of (1.12) into two steps. We first claim that for any $\varepsilon>0$, there exists $C(\varepsilon)>0$ such that

$$
\begin{equation*}
t_{\alpha}^{\frac{n}{2}-1-\varepsilon} d_{g}\left(x_{\alpha}, x\right)^{n-2-\varepsilon} z_{\alpha}(x) \leq C(\varepsilon) \tag{1.13}
\end{equation*}
$$

As a remark, note that (1.13) is true on any ball $B\left(x_{\alpha}, R t_{\alpha}^{-1}\right)$ with $R>0$ (see (1.8)). We therefore just have to prove (1.13) on $S^{n} \backslash B\left(x_{\alpha}, R t_{\alpha}^{-1}\right)$ for some $R>0$ (to be chosen later). We let $L_{\alpha}$ be the operator given by:

$$
L_{\alpha} u=\Delta_{g} u+\left(\alpha K_{n}^{-1}-\lambda_{\alpha} z_{\alpha}^{2^{*}-2}\right) u
$$

Since $L_{\alpha} z_{\alpha}=0$ and $z_{\alpha}>0$, the maximum principle holds for $L_{\alpha}$ (see [4]). Set

$$
\theta_{\alpha}(x)=\frac{C_{\alpha}}{\varphi(x)}\left(1-\left(x_{\alpha}, x\right)\right)^{\varepsilon+1-\frac{n}{2}}
$$

where $g=\varphi^{\frac{4}{n-2}} h$. We claim that for $R$ sufficiently large,

$$
L_{\alpha} \theta_{\alpha} \geq 0
$$

and that choosing suitably $C_{\alpha}$,

$$
\theta_{\alpha} \geq z_{\alpha} \quad \text { on } \partial B\left(x_{\alpha}, R t_{\alpha}^{-1}\right)
$$

We first prove that $L_{\alpha} \theta_{\alpha} \geq 0$ in $S^{n} \backslash B\left(x_{\alpha}, R t_{\alpha}^{-1}\right)$. We have

$$
L_{g} \theta_{\alpha}=\varphi^{1-2^{*}} L_{h}\left(\theta_{\alpha} \varphi\right)
$$

and

$$
\Delta_{h}\left(\theta_{\alpha} \varphi\right)=C_{\alpha} \Delta_{h}\left(\left(1-\left(x_{\alpha}, x\right)\right)^{\varepsilon+1-\frac{n}{2}}\right)
$$

Hence,

$$
\begin{aligned}
& \frac{1}{C_{\alpha}} \Delta_{h}\left(\theta_{\alpha} \varphi\right)= \\
& \quad-\frac{1}{\left(1-\left(x_{\alpha}, x\right)^{2}\right)^{\frac{n-1}{2}}} \partial_{r}\left(\left(1-\left(x_{\alpha}, x\right)^{2}\right)^{\frac{n-1}{2}} \partial_{r}\left(1-\left(x_{\alpha}, x\right)\right)^{\varepsilon+1-\frac{n}{2}}\right)
\end{aligned}
$$

Easy computations then lead to

$$
\begin{aligned}
& \left(1-\left(x_{\alpha}, x\right)\right) \frac{L_{\alpha} \theta_{\alpha}}{\theta_{\alpha}} \\
& =\left(1-\left(x_{\alpha}, x\right)\right)\left(\alpha K_{n}^{-1}-c_{n} S_{g}\right)-\lambda_{\alpha}\left(1-\left(x_{\alpha}, x\right)\right) z_{\alpha}^{2^{*}-2} \\
& \quad+\varepsilon \varphi^{2-2^{*}}\left(n-1-\varepsilon-(1+\varepsilon)\left(x_{\alpha}, x\right)\right) \\
& \geq\left(1-\left(x_{\alpha}, x\right)\right) K_{n}^{-1}\left(\alpha-B_{0}(g)\right)-C \lambda_{\alpha} d_{h}\left(x_{\alpha}, x\right)^{2} z_{\alpha}^{\frac{4}{n-2}} \\
& \quad+(n-2-2 \varepsilon) \varepsilon \varphi^{2-2^{*}}
\end{aligned}
$$

By (1.11),

$$
d_{h}\left(x_{\alpha}, x\right)^{2} z_{\alpha}^{\frac{4}{n-2}} \leq \varepsilon(R)
$$

when $d_{h}\left(x_{\alpha}, x\right) \geq R t_{\alpha}^{-1}$, and $\varepsilon(R) \rightarrow 0$ as $R \rightarrow \infty$. Therefore,

$$
\begin{aligned}
& \left(1-\left(x_{\alpha}, x\right)\right) \frac{L_{\alpha} \theta_{\alpha}}{\theta_{\alpha}} \geq \\
& \quad\left(1-\left(x_{\alpha}, x\right)\right) K_{n}^{-1}\left(\alpha-B_{0}(g)\right)-C \varepsilon(R)+(n-2-2 \varepsilon) \varepsilon \varphi^{2-2^{*}}
\end{aligned}
$$

and the RHS of this inequality is positive as $\alpha \rightarrow B_{0}(g)$ if we choose $R$ sufficiently large. This proves that $L_{\alpha} \theta_{\alpha} \geq 0$ for all $x \in S^{n} \backslash B\left(x_{\alpha}, R t_{\alpha}^{-1}\right)$. Let $x \in S^{n}$ be such that $d_{h}\left(x_{\alpha}, x\right)=R t_{\alpha}^{-1}$. We easily get that

$$
\theta_{\alpha}(x) \geq C C_{\alpha} t_{\alpha}^{(n-2-2 \varepsilon)}
$$

and since $z_{\alpha} \leq C t^{\frac{n}{2}-1}$, it follows that

$$
z_{\alpha} \leq \theta_{\alpha} \quad \text { on } \partial B\left(x_{\alpha}, R t_{\alpha}^{-1}\right)
$$

if we take $C_{\alpha}=C t_{\alpha}^{1+2 \varepsilon-\frac{n}{2}}$ for some $C>0$ independent of $\alpha$. According to the maximum principle, this leads to

$$
z_{\alpha} \leq \theta_{\alpha} \quad \text { on } S^{n} \backslash B\left(x_{\alpha}, R t_{\alpha}^{-1}\right)
$$

and hence, (1.13) is proved.
We now prove (1.12). We follow here [26] and we refer the reader to this reference for more details. Let $G_{\alpha}$ be the Green's function for the operator $\Delta_{g}+\alpha K_{n}^{-1}$, the only function $G_{\alpha}: S^{n} \times S^{n} \backslash\left\{(x, x) / x \in S^{n}\right\} \rightarrow \mathbb{R}$ which is such that:

$$
\Delta_{g, y} G_{\alpha}(x, y)+\alpha K_{n}^{-1} G_{\alpha}(x, y)=\delta_{x}
$$

By standard elliptic theory and standard properties of the Green's function, there exists some $C>0$, independent of $\alpha$, such that for any $x \neq y$ and any $\alpha \rightarrow B_{0}(g)$,

$$
\left|G_{\alpha}(x, y)\right| \leq C d_{g}(x, y)^{2-n}
$$

We first prove (1.12) on any compact subset $K$ of $S^{n} \backslash\left\{-x_{0}\right\}$. Let $\left(y_{\alpha}\right)$ be a sequence of points in such a $K$. Up to a subsequence, we may assume that $y_{\alpha} \rightarrow y_{0}$ as $\alpha \rightarrow B_{0}(g)$. Of course, $y_{0} \neq-x_{0}$. Since

$$
\Delta_{g} z_{\alpha}+\alpha K_{n}^{-1} z_{\alpha}=\lambda_{\alpha} z_{\alpha}^{2^{*}-1}
$$

we write that

$$
\begin{aligned}
z_{\alpha}\left(y_{\alpha}\right) & =\lambda_{\alpha} \int_{S^{n}} G_{\alpha}\left(y_{\alpha}, x\right) z_{\alpha}^{2^{*}-1} d v_{g} \\
& \leq C \int_{S^{n}} G_{\alpha}\left(y_{\alpha}, x\right) u_{\alpha}^{2^{*}-1} d v_{h}
\end{aligned}
$$

for some $C>0$ independent of $\alpha$. Through the stereographic projection $\pi_{-x_{\alpha}}$ of north pole $-x_{\alpha}$, this gives

$$
z_{\alpha}\left(y_{\alpha}\right) \leq C \int_{\mathbb{R}^{n}} G_{\alpha}\left(y_{\alpha}, \pi_{-x_{\alpha}}^{-1}(x)\right)\left(u_{\alpha} \circ \pi_{-x_{\alpha}}^{-1}\right)^{2^{*}-1}\left(1+|x|^{2}\right)^{-n} d x
$$

Since $y_{0} \neq-x_{0}$, and by standard properties of the Green's function, one easily checks that

$$
\begin{array}{ll}
G_{\alpha}\left(y_{\alpha}, \pi_{-x_{\alpha}}^{-1}(x)\right) \leq C(R)\left|\tilde{y}_{\alpha}-x\right|^{2-n} & \text { for any } x \in B(0, R) \\
G_{\alpha}\left(y_{\alpha}, \pi_{-x_{\alpha}}^{-1}(x)\right) \leq C(R) & \text { for any } x \in \mathbb{R}^{n} \backslash B(0, R)
\end{array}
$$

where $\tilde{y}_{\alpha}=\pi_{-x_{\alpha}}\left(y_{\alpha}\right), R$ is some positive real large enough and $C(R)$ depends only on $R$. Independently, by (1.7) and (1.13), one has that for any $\varepsilon>0$, there exists $C(\varepsilon)>0$ such that

$$
\left(u_{\alpha} \circ \pi_{-x_{\alpha}}^{-1}\right)(x) \leq C(\varepsilon) t_{\alpha}^{\frac{n}{2}-1}\left(\frac{1+t_{\alpha}^{2}|x|^{2}}{1+|x|^{2}}\right)^{\frac{\varepsilon+2-n}{2}}
$$

for any $x \in \mathbb{R}^{n}$. The above inequality then becomes for $R$ large enough

$$
\begin{aligned}
& z_{\alpha}\left(y_{\alpha}\right) \leq C(\varepsilon, R) t_{\alpha}^{\frac{n}{2}+1} \\
& \times \int_{B(0, R)}\left|\tilde{y}_{\alpha}-x\right|^{2-n}\left(1+t_{\alpha}^{2}|x|^{2}\right)^{\frac{(n+2)}{2(n-2)} \varepsilon-1-\frac{n}{2}}\left(1+|x|^{2}\right)^{\frac{2-n}{2}-\frac{(n+2)}{2(n-2)} \varepsilon} d x \\
& \quad+C(\varepsilon, R) \int_{\mathbb{R}^{n} \backslash B(0, R)}\left(1+t_{\alpha}^{2}|x|^{2}\right)^{\frac{(n+2)}{2(n-2)} \varepsilon-1-\frac{n}{2}}\left(1+|x|^{2}\right)^{\frac{2-n}{2}-\frac{(n+2)}{2(n-2)} \varepsilon} d x
\end{aligned}
$$

where $C(\varepsilon, R)$ depends only on $R$ and $\varepsilon$. We take $\varepsilon=\frac{n-2}{n+2}$. Setting $y=t_{\alpha} x$, we get

$$
\begin{aligned}
z_{\alpha}\left(y_{\alpha}\right) \leq & C t_{\alpha}^{\frac{n}{2}-1} \int_{\mathbb{R}^{n}}\left|t_{\alpha} \tilde{y}_{\alpha}-y\right|^{2-n}\left(1+|y|^{2}\right)^{-\frac{n+1}{2}}\left(1+t_{\alpha}^{-2}|y|^{2}\right)^{\frac{1-n}{2}} d y \\
& +o\left(t_{\alpha}^{1-\frac{n}{2}}\right)
\end{aligned}
$$

The proof splits now into the study of two cases. In the first one, we assume that, after passing to a subsequence, $\lim _{\alpha \rightarrow B_{0}(g)} t_{\alpha} \tilde{y}_{\alpha}=\tilde{y}$. Then, by Lebesgue's theorem, we get that for $\varepsilon$ small enough,

$$
z_{\alpha}\left(y_{\alpha}\right) \leq C t_{\alpha}^{\frac{n}{2}-1} \int_{\mathbb{R}^{n}}|\tilde{y}-y|^{2-n}\left(1+|y|^{2}\right)^{-\frac{n+1}{2}} d y
$$

Since $d_{g}\left(x_{\alpha}, y_{\alpha}\right) \leq C\left|\tilde{y}_{\alpha}\right| \leq C t_{\alpha}^{-1}$ and $z_{\alpha}\left(x_{\alpha}\right) \leq C t_{\alpha}^{\frac{n}{2}-1}$, it follows that

$$
d_{g}\left(x_{\alpha}, y_{\alpha}\right)^{n-2} z_{\alpha}\left(x_{\alpha}\right) z_{\alpha}\left(y_{\alpha}\right) \leq C
$$

In the second case, we assume that $t_{\alpha}\left|\tilde{y}_{\alpha}\right| \rightarrow+\infty$ as $\alpha \rightarrow B_{0}(g)$. Then

$$
\begin{aligned}
z_{\alpha}\left(y_{\alpha}\right) \leq & C t_{\alpha}^{1-\frac{n}{2}}\left|\tilde{y}_{\alpha}\right|^{2-n} \int_{\mathbb{R}^{n} \backslash B\left(t_{\alpha} \tilde{y}_{\alpha}, \frac{t_{\alpha}\left|\bar{y}_{\alpha}\right|}{2}\right)}\left(1+|y|^{2}\right)^{-\frac{n+1}{2}} d y+o\left(t_{\alpha}^{1-\frac{n}{2}}\right) \\
& +C t_{\alpha}^{-2-\frac{n}{2}}\left|\tilde{y}_{\alpha}\right|^{-1-n} \int_{B\left(t_{\alpha} \tilde{y}_{\alpha}, \frac{t_{\alpha}\left|\bar{y}_{\alpha}\right|}{2}\right)}\left|y-t_{\alpha} \tilde{y}_{\alpha}\right|^{2-n} d y \\
\leq & C t_{\alpha}^{1-\frac{n}{2}}\left|\tilde{y}_{\alpha}\right|^{2-n}
\end{aligned}
$$

This concludes the proof of (2.12) on any compact subset of $S^{n} \backslash\left\{-x_{0}\right\}$. Since $t_{\alpha}^{\frac{n}{2}-1} z_{\alpha}$ verifies

$$
\Delta_{g}\left(t_{\alpha}^{\frac{n}{2}-1} z_{\alpha}\right)+\alpha K_{n}^{-1}\left(t_{\alpha}^{\frac{n}{2}-1} z_{\alpha}\right)=\lambda_{\alpha} t_{\alpha}^{-2}\left(t_{\alpha}^{\frac{n}{2}-1} z_{\alpha}\right)^{2^{*}-1}
$$

standard Harnack's inequalities conclude the proof of (2.12).

## 1.3 - Proof of Theorem 0.3 (continued)

As one easily checks, (1.12), together with (1.1), (1.2) and (1.7), gives that

$$
\begin{aligned}
& z_{\alpha}\left(\Phi_{\alpha}(x)\right)\left|\operatorname{det} d \Phi_{\alpha}\right|(x)^{\frac{1}{2^{*}}} \\
& =\left(2 t_{\alpha}\right)^{\frac{n}{2}-1} z_{\alpha}\left(\Phi_{\alpha}(x)\right)\left[\left(1+t_{\alpha}^{2}\right)+\left(t_{\alpha}^{2}-1\right)\left(x, x_{\alpha}\right)\right]^{1-\frac{n}{2}} \\
& =\left(\frac{t_{\alpha}^{2}+1}{2 t_{\alpha}}\right)^{\frac{n}{2}-1} z_{\alpha}\left(\Phi_{\alpha}(x)\right)\left[1-\frac{t_{\alpha}^{2}-1}{t_{\alpha}^{2}+1}\left(x_{\alpha}, \Phi_{\alpha}(x)\right)\right]^{\frac{n}{2}-1} \\
& \leq C t_{\alpha}^{\frac{n}{2}-1} z_{\alpha}\left(\Phi_{\alpha}(x)\right)\left[1-\left(x_{\alpha}, \Phi_{\alpha}(x)\right)\right]^{\frac{n}{2}-1}+C t_{\alpha}^{1-\frac{n}{2}} z_{\alpha}\left(\Phi_{\alpha}(x)\right) \\
& \leq C
\end{aligned}
$$

This proves the last part of Theorem 0.3. Moreover, it easily follows from standard elliptic theory that

$$
\lim _{\alpha \rightarrow B_{0}(g)} t_{\alpha}^{\frac{n}{2}-1} z_{\alpha}=\lambda G\left(x_{0}, x\right) \quad \text { in } C_{l o c}^{2}\left(S^{n} \backslash\left\{x_{0}\right\}\right)
$$

To compute $\lambda$, we just pick a point $x \neq x_{0} \in S^{n}$ and write by the Green's formula that

$$
\begin{aligned}
& t_{\alpha}^{\frac{n}{2}-1} z_{\alpha}(x) \\
& =\lambda_{\alpha} t_{\alpha}^{\frac{n}{2}-1} \int_{S^{n}} G_{\alpha}(x, y) z_{\alpha}(y)^{2^{*}-1} d v_{g}(y) \\
& =\lambda_{\alpha} t_{\alpha}^{\frac{n}{2}-1} \int_{S^{n}} G_{\alpha}(x, y) u_{\alpha}(y)^{2^{*}-1} \varphi(y) d v_{h}(y) \\
& \left.=\lambda_{\alpha} t_{\alpha}^{\frac{n}{2}-1} \int_{S^{n}} G_{\alpha}\left(x, \Phi_{\alpha}(y)\right) v_{\alpha}(y)^{2^{*}-1} \varphi \circ \Phi_{\alpha}(y) \right\rvert\, \text { det }\left.d \Phi_{\alpha}\right|^{\frac{1}{2^{*}}} d v_{h}(y) \\
& =2^{\frac{n}{2}-1} \lambda_{\alpha} \frac{t_{\alpha}^{n-2}}{\left(t_{\alpha}^{2}+1\right)^{\frac{n}{2}-1}} \\
& \quad \times \int_{S^{n}} G_{\alpha}\left(x, \Phi_{\alpha}(y)\right) v_{\alpha}(y)^{2^{*}-1} \varphi \circ \Phi_{\alpha}(y)\left[1+\frac{t_{\alpha}^{2}-1}{t_{\alpha}^{2}+1}\left(x, x_{\alpha}\right)\right]^{1-\frac{n}{2}} d v_{h}(y)
\end{aligned}
$$

Since $\left(v_{\alpha}\right)$ is bounded (see section 1.1) and converges pointwise to $\omega_{n}^{-\frac{1}{2^{*}}}$, and $\lambda_{\alpha} \rightarrow K_{n}^{-1}$, we obtain by Lebesgue's theorem that

$$
\begin{aligned}
& \lim _{\alpha \rightarrow B_{0}(g)} t^{\frac{n}{2}-1} z_{\alpha}(x) \\
& =2^{\frac{n}{2}-1} K_{n}^{-1} G\left(x_{0}, x\right) \varphi\left(x_{0}\right) \omega_{n}^{-1+\frac{1}{2^{*}}} \int_{S^{n}}\left[1+\left(x, x_{0}\right)\right]^{1-\frac{n}{2}} d v_{h} \\
& =2^{n} K_{n}^{-1} G\left(x_{0}, x\right) \varphi\left(x_{0}\right) \omega_{n}^{-1+\frac{1}{2^{*}}} \int_{\mathbb{R}^{n}}\left(1+|y|^{2}\right)^{-1-\frac{n}{2}} d y \\
& =\varphi\left(x_{0}\right) \omega_{n}^{-\frac{1}{2^{*}}} 2^{n-2} \omega_{n-1}(n-2) G\left(x_{0}, x\right)
\end{aligned}
$$

This ends the proof of the theorem.

## 2 - Proof of Theorem 0.4

We begin by setting up some notations we use in the sequel. For $\left(x_{\alpha}\right)$ and $\left(t_{\alpha}\right)$ given by Theorem 0.3, we let

$$
\Phi_{\alpha}=\Phi_{x_{\alpha}, t_{\alpha}}
$$

Then, for $\pi_{-x_{\alpha}}$ the stereographic projection of north pole $-x_{\alpha}$, we let

$$
\tilde{S}_{\alpha}=S_{g} \circ \pi_{-x_{\alpha}}^{-1}, \quad \tilde{\varphi}_{\alpha}=\varphi \circ \pi_{-x_{\alpha}}^{-1}, \quad \tilde{v}_{\alpha}=v_{\alpha} \circ \pi_{-x_{\alpha}}^{-1}
$$

and, for $\pi_{-x_{0}}$ the stereographic projection of north pole $-x_{0}$, we let

$$
\tilde{S}_{g}=S_{g} \circ \pi_{-x_{0}}^{-1}, \quad \tilde{\varphi}=\varphi \circ \pi_{-x_{0}}^{-1}, \quad \tilde{G}\left(x_{0}, .\right)=G\left(x_{0}, \pi_{-x_{0}}^{-1}(.)\right)
$$

A main tool in the proof of Theorem 0.4 is the Kazdan-Warner identity [21]: if $f$ and $u$ in $C^{\infty}\left(S^{n}\right)$ verify

$$
L_{h} u=f u^{2^{*}-1}
$$

then for any first eigenfunction $\psi$ of $\Delta_{h}$ associated to the first nonzero eigenvalue $\lambda_{1}=n$ of $\Delta_{h}$,

$$
\int_{S^{n}}(\nabla f, \nabla \psi)_{h} u^{2^{*}} d v_{h}=0
$$

We apply this identity to equation $\left(F_{\alpha}\right)$ with $\psi_{\alpha}(x)=\left(x_{\alpha}, x\right)$. Integrating by parts, this leads to
$\int_{S^{n}}\left(\nabla\left[\left(c_{n} S_{g} \circ \Phi_{\alpha}-\alpha K_{n}^{-1}\right)\left(\varphi \circ \Phi_{\alpha}\right)^{2^{*}-2}\right], \nabla\left(x_{\alpha}, x\right)\right)_{h}\left|\operatorname{det} d \Phi_{\alpha}\right|^{\frac{2}{n}} v_{\alpha}^{2} d v_{h}$
$+\int_{S^{n}}\left(\nabla\left[\left|\operatorname{det} d \Phi_{\alpha}\right|^{\frac{2}{n}}\right], \nabla\left(x_{\alpha}, x\right)\right)_{h}\left(c_{n} S_{g} \circ \Phi_{\alpha}-\alpha K_{n}^{-1}\right)\left(\varphi \circ \Phi_{\alpha}\right)^{2^{*}-2} v_{\alpha}^{2} d v_{h}$
$=2 \int_{S^{n}}\left(c_{n} S_{g} \circ \Phi_{\alpha}-\alpha K_{n}^{-1}\right)\left(\varphi \circ \Phi_{\alpha}\right)^{2^{*}-2}\left(x_{\alpha}, x\right)\left|\operatorname{det} d \Phi_{\alpha}\right|^{\frac{2}{n}} v_{\alpha}^{2} d v_{h}$
With the help of relations (1.3), (1.4), (1.5), and thanks to the fact that $\left(\pi_{-x_{\alpha}}^{-1}\right)^{*} h=4\left(1+|x|^{2}\right)^{-2} \xi$, (2.1) may be written as

$$
\begin{equation*}
I_{\alpha}+I I_{\alpha}=I I I_{\alpha} \tag{2.2}
\end{equation*}
$$

where

$$
\begin{aligned}
& I_{\alpha}=\frac{1}{2 t_{\alpha}} \int_{\mathbb{R}^{n}} \frac{\left(\nabla\left[\left(c_{n} \tilde{S}_{\alpha}-\alpha K_{n}^{-1}\right) \tilde{\varphi}_{\alpha}^{2^{*}-2}\right]\left(\frac{x}{t_{\alpha}}\right), x\right) \tilde{v}_{\alpha}^{2}}{\left(t_{\alpha}^{2}+|x|^{2}\right)^{2}\left(1+|x|^{2}\right)^{n-2}} d x \\
& I I_{\alpha}=t_{\alpha}^{2} \int_{\mathbb{R}^{n}} \frac{\left(c_{n} \tilde{S}_{\alpha}\left(\frac{x}{t_{\alpha}}\right)-\alpha K_{n}^{-1}\right) \tilde{\varphi}_{\alpha}\left(\frac{x}{t_{\alpha}}\right)^{2^{*}-2} \tilde{v}_{\alpha}^{2}}{\left(t_{\alpha}^{2}+|x|^{2}\right)^{3}\left(1+|x|^{2}\right)^{n-2}} d x \\
& I I I_{\alpha}=\int_{\mathbb{R}^{n}} \frac{\left(c_{n} \tilde{S}_{\alpha}\left(\frac{x}{t_{\alpha}}\right)-\alpha K_{n}^{-1}\right) \tilde{\varphi}_{\alpha}\left(\frac{x}{t_{\alpha}}\right)^{2^{*}-2}|x|^{2} \tilde{v}_{\alpha}^{2}}{\left(t_{\alpha}^{2}+|x|^{2}\right)^{3}\left(1+|x|^{2}\right)^{n-2}} d x
\end{aligned}
$$

We now derive useful relations for $\tilde{v}_{\alpha}$. Let $x_{0} \in \operatorname{Max} S_{g}$ and $G\left(x_{0}, x\right)$ be the Green's function of $\Delta_{g}+B_{0}(g) K_{n}^{-1}$ at $x_{0}$. We set

$$
H\left(x_{0}, x\right)=\frac{1}{2^{n-2} \omega_{n-1}(n-2) \varphi(x) \varphi\left(x_{0}\right)}\left(\frac{1-\left(x_{0}, x\right)}{2}\right)^{1-\frac{n}{2}}
$$

so that

$$
L_{g} H\left(x_{0}, x\right)=\delta_{x_{0}}
$$

where the conformal Laplacian $L_{g}$ is given by $L_{g}=\Delta_{g}+c_{n} S_{g}$. We write then

$$
\begin{equation*}
G\left(x_{0}, x\right)=\frac{1}{2^{n-2} \omega_{n-1}(n-2) \varphi(x) \varphi\left(x_{0}\right)}\left[\left(\frac{1-\left(x_{0}, x\right)}{2}\right)^{1-\frac{n}{2}}+\sigma(x)\right] \tag{2.3}
\end{equation*}
$$

Hence, $\sigma$ satisfies in the sense of distributions

$$
\begin{equation*}
L_{h} \sigma=\left(c_{n} S_{g}-B_{0}(g) K_{n}^{-1}\right) \varphi^{2^{*}-2}\left[\left(\frac{1-\left(x_{0}, x\right)}{2}\right)^{1-\frac{n}{2}}+\sigma(x)\right] \tag{2.4}
\end{equation*}
$$

By standard elliptic theory, since

$$
\left|c_{n} S_{g}-B_{0}(g) K_{n}^{-1}\right|=c_{n}\left|S_{g}(x)-S_{g}\left(x_{0}\right)\right| \leq C d_{h}\left(x_{0}, x\right)^{2}
$$

we find that $\sigma \in C^{1}\left(S^{n}\right)$ for $n=4$ and $\sigma \in C^{0}\left(S^{n}\right)$ for $n=5$. We set $\tilde{\sigma}=\sigma \circ \pi_{-x_{0}}^{-1}$, and come back to the study of the $\tilde{v}_{\alpha}$ 's. We already know by Theorem 0.3 that $\tilde{v}_{\alpha}$ is bounded uniformly in $\alpha$. We claim now that

$$
\begin{equation*}
\tilde{v}_{\alpha}\left(t_{\alpha} x\right) \rightarrow \omega_{n}^{-\frac{1}{2^{*}}}\left[1+|x|^{n-2}\left(1+|x|^{2}\right)^{1-\frac{n}{2}} \tilde{\sigma}(x)\right] \quad \text { in } C_{l o c}^{0}\left(\mathbb{R}^{n} \backslash\{0\}\right) \tag{2.5}
\end{equation*}
$$

This follows from Theorem 0.3. Indeed, using in particular (1.4) and (1.5),

$$
\begin{aligned}
\tilde{v}_{\alpha}\left(t_{\alpha} x\right) & =v_{\alpha} \circ \Phi_{\alpha}^{-1} \circ \pi_{-x_{\alpha}}^{-1}(x) \\
& =u_{\alpha} \circ \pi_{-x_{\alpha}}^{-1}(x)\left|\operatorname{det} d \Phi_{\alpha}\right|\left(\pi_{-x_{\alpha}}\left(t_{\alpha} x\right)\right)^{\frac{1}{2^{*}}} \\
& =t_{\alpha}^{\frac{n}{2}-1} u_{\alpha} \circ \pi_{-x_{\alpha}}^{-1}(x)\left(t_{\alpha}^{-2}+|x|^{2}\right)^{\frac{n}{2}-1}\left(1+|x|^{2}\right)^{1-\frac{n}{2}} \\
& \rightarrow \omega_{n}^{-\frac{1}{2^{*}}}\left[1+|x|^{n-2}\left(1+|x|^{2}\right)^{1-\frac{n}{2}} \tilde{\sigma}(x)\right] \text { in } C_{l o c}^{0}\left(\mathbb{R}^{n} \backslash\{0\}\right)
\end{aligned}
$$

by Theorem 0.3. We derive now an estimate of $\tilde{v}_{\alpha}\left(t_{\alpha} x\right)$ near the origin. More precisely, we claim that

$$
\begin{equation*}
\lim _{R \rightarrow+\infty} \lim _{\alpha \rightarrow B_{0}(g)} \sup _{x \in B\left(0, R^{-1}\right)}\left|\tilde{v}_{\alpha}\left(t_{\alpha} x\right)-\omega_{n}^{-\frac{1}{2^{*}}}\right|=0 \tag{2.6}
\end{equation*}
$$

Let $y_{\alpha} \in B\left(0, R^{-1}\right)$ be such that

$$
\left|\tilde{v}_{\alpha}\left(t_{\alpha} y_{\alpha}\right)-\omega_{n}^{-\frac{1}{2^{*}}}\right|=\sup _{x \in B\left(0, R^{-1}\right)}\left|\tilde{v}_{\alpha}\left(t_{\alpha} x\right)-\omega_{n}^{-\frac{1}{2^{*}}}\right|
$$

We want to prove that

$$
\lim _{\alpha \rightarrow B_{0}(g)}\left|\tilde{v}_{\alpha}\left(t_{\alpha} y_{\alpha}\right)-\omega_{n}^{-\frac{1}{2^{*}}}\right| \leq \varepsilon(R)
$$

where $\varepsilon(R) \rightarrow 0$ as $R \rightarrow+\infty$. The proof here splits into three cases. In the first one we assume that $\left|y_{\alpha}\right| \nrightarrow 0$ as $\alpha \rightarrow B_{0}(g)$. Up to the extraction of a subsequence, $y_{\alpha} \rightarrow y, y \neq 0$, so that by (2.5), as $\alpha \rightarrow B_{0}(g)$,

$$
\begin{aligned}
\tilde{v}_{\alpha}\left(t_{\alpha} y_{\alpha}\right) \rightarrow & \omega_{n}^{-\frac{1}{2^{*}}}\left[1+|y|^{n-2}\left(1+|y|^{2}\right)^{\frac{n}{2}-1} \tilde{\sigma}(y)\right] \\
& =\omega_{n}^{-\frac{1}{2^{*}}}+\varepsilon(R)
\end{aligned}
$$

according to standard properties of the Green's function. In the second case we assume that $t_{\alpha} y_{\alpha} \rightarrow y$ after passing to a subsequence. By (1.8), we have

$$
\tilde{v}_{\alpha}\left(t_{\alpha} y_{\alpha}\right) \rightarrow \omega_{n}^{-\frac{1}{2^{*}}}
$$

as $\alpha \rightarrow B_{0}(g)$. In the third case we assume that $\left|y_{\alpha}\right| \rightarrow 0$ and $t_{\alpha}\left|y_{\alpha}\right| \rightarrow+\infty$ as $\alpha \rightarrow B_{0}(g)$. The Green's formula on $\mathbb{R}^{n}$ gives that

$$
\begin{aligned}
\tilde{v}_{\alpha}\left(t_{\alpha} y_{\alpha}\right)= & \frac{2^{1-\frac{n}{2}}}{\omega_{n-1}(n-2)}\left(1+\left|t_{\alpha} y_{\alpha}\right|^{2}\right)^{\frac{n}{2}-1} \\
& \times \int_{\mathbb{R}^{n}}\left|x-t_{\alpha} y_{\alpha}\right|^{2-n} \Delta_{\xi}\left(2^{\frac{n}{2}-1}\left(1+|x|^{2}\right)^{1-\frac{n}{2}} \tilde{v}_{\alpha}(x)\right) d x
\end{aligned}
$$

where $\Delta_{\xi}$ is the Laplacian with respect to the Euclidean metric. Recall that

$$
\left(\pi_{-x_{\alpha}}^{-1}\right)^{*} h=4\left(1+|x|^{2}\right)^{-2} \xi
$$

Equation $\left(F_{\alpha}\right)$ together with (1.4) and (1.5) then gives that

$$
\begin{aligned}
& \left(\frac{1+|x|^{2}}{2}\right)^{\frac{n}{2}+1} \Delta_{\xi}\left(2^{\frac{n}{2}-1}\left(1+|x|^{2}\right)^{1-\frac{n}{2}} \tilde{v}_{\alpha}(x)\right)=\lambda_{\alpha} \tilde{v}_{\alpha}(x)^{2^{*}-1} \\
& \quad-\left(\alpha K_{n}^{-1}-c_{n} \tilde{S}_{\alpha}\left(\frac{x}{t_{\alpha}}\right)\right) \tilde{\varphi}_{\alpha}\left(\frac{x}{t_{\alpha}}\right)^{2^{*}-2} t_{\alpha}^{2}\left(1+|x|^{2}\right)^{2}\left(t_{\alpha}^{2}+|x|^{2}\right)^{-2} \tilde{v}_{\alpha}(x)
\end{aligned}
$$

Coming back to the above Green's formula, we obtain

$$
\begin{aligned}
\tilde{v}_{\alpha}\left(t_{\alpha} y_{\alpha}\right)= & \frac{4}{\omega_{n-1}(n-2)} \lambda_{\alpha}\left(1+\left|t_{\alpha} y_{\alpha}\right|^{2}\right)^{\frac{n}{2}-1} A_{\alpha} \\
& -\frac{4 t_{\alpha}^{2}}{\omega_{n-1}(n-2)}\left(1+\left|t_{\alpha} y_{\alpha}\right|^{2}\right)^{\frac{n}{2}-1} B_{\alpha}
\end{aligned}
$$

where

$$
\begin{aligned}
& A_{\alpha}=\int_{\mathbb{R}^{n}}\left|x-t_{\alpha} y_{\alpha}\right|^{2-n}\left(1+|x|^{2}\right)^{-1-\frac{n}{2}} \tilde{v}_{\alpha}(x)^{2^{*}-1} d x \\
& B_{\alpha}=\int_{\mathbb{R}^{n}}\left|x-t_{\alpha} y_{\alpha}\right|^{2-n} C_{\alpha}\left(\frac{x}{t_{\alpha}}\right)\left(t_{\alpha}^{2}+|x|^{2}\right)^{-2}\left(1+|x|^{2}\right)^{1-\frac{n}{2}} \tilde{v}_{\alpha}(x) d x
\end{aligned}
$$

and

$$
C_{\alpha}(x)=\left(\alpha K_{n}^{-1}-c_{n} \tilde{S}_{\alpha}(x)\right) \tilde{\varphi}_{\alpha}(x)^{2^{*}-2}
$$

Regarding the first term in the RHS of the above relation, we have that

$$
\begin{aligned}
\left|t_{\alpha} y_{\alpha}\right|^{n-2} A_{\alpha} & =\int_{\mathbb{R}^{n}}\left|\frac{x}{t_{\alpha}\left|y_{\alpha}\right|}-\frac{y_{\alpha}}{\left|y_{\alpha}\right|}\right|^{2-n}\left(1+|x|^{2}\right)^{-1-\frac{n}{2}} \tilde{v}_{\alpha}(x)^{2^{*}-1} d x \\
& \rightarrow \omega_{n}^{-1+\frac{1}{2^{*}}} \int_{\mathbb{R}^{n}}\left(1+|x|^{2}\right)^{-1-\frac{n}{2}} d x=\frac{\omega_{n-1}}{n} \omega_{n}^{-1+\frac{1}{2^{*}}}
\end{aligned}
$$

by Lebesgue's theorem. Regarding the second term, we get by Theorem 0.3, and performing the change of variables $x=t_{\alpha}\left|y_{\alpha}\right| y$, that

$$
\begin{aligned}
& t_{\alpha}^{n}\left|y_{\alpha}\right|^{n-2} B_{\alpha} \\
& \quad \leq C t_{\alpha}^{2} \int_{\mathbb{R}^{n}}\left|\frac{x}{t_{\alpha}\left|y_{\alpha}\right|}-\frac{y_{\alpha}}{\left|y_{\alpha}\right|}\right|^{2-n}\left(t_{\alpha}^{2}+|x|^{2}\right)^{-2}\left(1+|x|^{2}\right)^{1-\frac{n}{2}} d x \\
& \quad \leq C\left|y_{\alpha}\right|^{2} \int_{\mathbb{R}^{n}}\left|y-\frac{y_{\alpha}}{\left|y_{\alpha}\right|}\right|^{2-n}\left(t_{\alpha}^{-2}\left|y_{\alpha}\right|^{-2}+|y|^{2}\right)^{1-\frac{n}{2}}\left(1+\left|y_{\alpha}\right|^{2}|y|^{2}\right)^{-2} d y \\
& \quad \leq C\left|y_{\alpha}\right|^{2}
\end{aligned}
$$

Since $\left|y_{\alpha}\right| \rightarrow 0$ and $\lambda_{\alpha} \rightarrow K_{n}^{-1}$, we get that

$$
\tilde{v}_{\alpha}\left(t_{\alpha} y_{\alpha}\right) \rightarrow \omega_{n}^{-\frac{1}{2^{*}}}
$$

as $\alpha \rightarrow B_{0}(g)$. Thus, (2.6) is proved.
Going on with the proof of Theorem 0.4, we divide it into two parts. On the one hand, we deal with dimensions $n \geq 6$. On the other hand, we deal with dimensions $n=4,5$.

## 2.1-The case $n \geq 6$

We need here one more ingredient to estimate the speed of convergence of $x_{\alpha}$ to $x_{0}$ as $\alpha \rightarrow B_{0}(g)$. By the standard Sobolev inequality on $\left(S^{n}, h\right)$,

$$
1=\left(\int_{S^{n}} v_{\alpha}^{2^{*}} d v_{h}\right)^{\frac{2}{2^{*}}} \leq K_{n}\left[\int_{S^{n}}\left|\nabla v_{\alpha}\right|_{h}^{2} d v_{h}+\frac{n(n-2)}{4} \int_{S^{n}} v_{\alpha}^{2} d v_{h}\right]
$$

Together with equation $\left(F_{\alpha}\right)$, this gives

$$
\begin{equation*}
K_{n}^{-1}-\lambda_{\alpha} \leq \int_{S^{n}}\left(c_{n} S_{g} \circ \Phi_{\alpha}-\alpha K_{n}^{-1}\right)\left(\varphi \circ \Phi_{\alpha}\right)^{2^{*}-2}\left|\operatorname{det} d \Phi_{\alpha}\right|^{\frac{2}{n}} v_{\alpha}^{2} d v_{h} \tag{2.7}
\end{equation*}
$$

Independently, by the definition of $\lambda_{\alpha}$, we have that for any $\alpha<B_{0}(g)$

$$
\begin{aligned}
& \int_{S^{n}}\left|\nabla\left(\varphi^{-1}\left|\operatorname{det} d \Phi_{x_{0}, t_{\alpha}}\right|\left(\Phi_{x_{0}, t_{\alpha}}^{-1}(x)\right)^{-\frac{1}{2^{*}}}\right)\right|_{g}^{2} d v_{g} \\
& +\alpha K_{n}^{-1} \int_{S^{n}} \varphi^{-2}\left|\operatorname{det} d \Phi_{x_{0}, t_{\alpha}}\right|\left(\Phi_{x_{0}, t_{\alpha}}^{-1}(x)\right)^{-\frac{2}{2^{*}}} d v_{g} \\
& \quad \geq \lambda_{\alpha}\left(\int_{S^{n}} \varphi^{-2^{*}}\left|\operatorname{det} d \Phi_{x_{0}, t_{\alpha}}\right|\left(\Phi_{x_{0}, t_{\alpha}}^{-1}(x)\right)^{-1} d v_{g}\right)^{\frac{2}{2^{*}}}
\end{aligned}
$$

where $t_{\alpha}$ is given by Theorem 0.3 . By conformal change of the metric, this inequality becomes

$$
\begin{aligned}
& \int_{S^{n}}\left|\operatorname{det} d \Phi_{x_{0}, t_{\alpha}}\right|\left(\Phi_{x_{0}, t_{\alpha}}^{-1}(x)\right)^{-\frac{1}{2^{*}}} L_{h}\left(\left|\operatorname{det} d \Phi_{x_{0}, t_{\alpha}}\right|\left(\Phi_{x_{0}, t_{\alpha}}^{-1}(x)\right)^{-\frac{1}{2^{*}}}\right) d v_{h} \\
& \geq \int_{S^{n}}\left(c_{n} S_{g}-\alpha K_{n}^{-1}\right) \varphi^{2^{*}-2}\left|\operatorname{det} d \Phi_{x_{0}, t_{\alpha}}\right|\left(\Phi_{x_{0}, t_{\alpha}}^{-1}(x)\right)^{-\frac{2}{2^{*}}} d v_{h} \\
& \quad+\lambda_{\alpha}\left(\int_{S^{n}}\left|\operatorname{det} d \Phi_{x_{0}, t_{\alpha}}\right|\left(\Phi_{x_{0}, t_{\alpha}}^{-1}(x)\right)^{-1} d v_{h}\right)^{\frac{2}{2^{*}}}
\end{aligned}
$$

As easily checked,

$$
\begin{aligned}
& L_{h}\left(\left|\operatorname{det} d \Phi_{x_{0}, t_{\alpha}}\right|\left(\Phi_{x_{0}, t_{\alpha}}^{-1}(x)\right)^{-\frac{1}{2^{*}}}\right)= \\
& \left.\quad \frac{n(n-2)}{4} \right\rvert\, \text { det } d \Phi_{x_{0}, t_{\alpha}} \left\lvert\,\left(\Phi_{x_{0}, t_{\alpha}}^{-1}(x)\right)^{-1+\frac{1}{2^{*}}}\right.
\end{aligned}
$$

and

$$
\int_{S^{n}}\left|\operatorname{det} d \Phi_{x_{0}, t_{\alpha}}\right|\left(\Phi_{x_{0}, t_{\alpha}}^{-1}(x)\right)^{-1} d v_{h}=\omega_{n}
$$

Therefore,

$$
\begin{aligned}
& \omega_{n}^{-\frac{2}{2^{*}}} \int_{S^{n}}\left(c_{n} S_{g}-\alpha K_{n}^{-1}\right) \varphi^{2^{*}-2}\left|\operatorname{det} d \Phi_{x_{0}, t_{\alpha}}\right|\left(\Phi_{x_{0}, t_{\alpha}}^{-1}(x)\right)^{-\frac{2}{2^{*}}} d v_{h} \\
& \quad \leq K_{n}^{-1}-\lambda_{\alpha}
\end{aligned}
$$

and

$$
\begin{aligned}
& \omega_{n}^{-\frac{2}{2^{*}}} \int_{S^{n}}\left(c_{n} S_{g} \circ \Phi_{x_{0}, t_{\alpha}}-\alpha K_{n}^{-1}\right)\left(\varphi \circ \Phi_{x_{0}, t_{\alpha}}\right)^{2^{*}-2}\left|\operatorname{det} d \Phi_{x_{0}, t_{\alpha}}\right|^{\frac{2}{n}} d v_{h} \\
& \quad \leq K_{n}^{-1}-\lambda_{\alpha}
\end{aligned}
$$

Combining this inequality with (2.7), we obtain

$$
\begin{align*}
& \left.\omega_{n}^{-\frac{2}{2^{*}}} \int_{S^{n}}\left(c_{n} S_{g} \circ \Phi_{x_{0}, t_{\alpha}}-\alpha K_{n}^{-1}\right)\left(\varphi \circ \Phi_{x_{0}, t_{\alpha}}\right)^{2^{*}-2} \right\rvert\, \text { det }\left.d \Phi_{x_{0}, t_{\alpha}}\right|^{\frac{2}{n}} d v_{h} \\
& \quad \leq \int_{S^{n}}\left(c_{n} S_{g} \circ \Phi_{\alpha}-\alpha K_{n}^{-1}\right)\left(\varphi \circ \Phi_{\alpha}\right)^{2^{*}-2}\left|\operatorname{det} d \Phi_{\alpha}\right|^{\frac{2}{n}} v_{\alpha}^{2} d v_{h} \tag{2.8}
\end{align*}
$$

We now prove the theorem when $n \geq 7$, and leave details to the reader when $n=6$ (see the end of this subsection). First, we compute the LHS term in (2.8). Through the stereographic projection $\pi_{-x_{0}}$, we get using (1.4) and (1.5), and performing the change of variables $x=t_{\alpha} y$, that

LHS of (2.8)

$$
\begin{aligned}
= & 2^{n} \omega_{n}^{-\frac{2}{2^{*}}} t_{\alpha}^{2} \int_{\mathbb{R}^{n}} \frac{\left(c_{n} \tilde{S}_{g}\left(\frac{x}{t_{\alpha}}\right)-\alpha K_{n}^{-1}\right) \tilde{\varphi}\left(\frac{x}{t_{\alpha}}\right)^{2^{*}-2}}{\left(t_{\alpha}^{2}+|x|^{2}\right)^{2}\left(1+|x|^{2}\right)^{n-2}} d x \\
= & 2^{n} \omega_{n}^{-\frac{2}{2^{*}}} t_{\alpha}^{2-n}\left(B_{0}(g)-\alpha\right) K_{n}^{-1} \int_{\mathbb{R}^{n}} \frac{\tilde{\varphi}(y)^{2^{*}-2}}{\left(1+|y|^{2}\right)^{2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{n-2}} d y \\
& +2^{n} \omega_{n}^{-\frac{2}{2^{*}}} c_{n} t_{\alpha}^{2-n} \int_{\mathbb{R}^{n}} \frac{\left(\tilde{S}_{g}(y)-\tilde{S}_{g}(0)\right) \tilde{\varphi}(y)^{2^{*}-2}}{\left(1+|y|^{2}\right)^{2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{n-2}} d y
\end{aligned}
$$

On the one hand,

$$
\begin{aligned}
\int_{\mathbb{R}^{n}} & \tilde{\varphi}(y)^{2^{*}-2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2-n}\left(1+|y|^{2}\right)^{-2} d y \\
& =\tilde{\varphi}(0)^{2^{*}-2} t_{\alpha}^{n-4} \int_{\mathbb{R}^{n}}\left(1+|y|^{2}\right)^{2-n} d y+o\left(t_{\alpha}^{n-4}\right)
\end{aligned}
$$

On the other hand, writing that

$$
\tilde{S}_{g}(y)-\tilde{S}_{g}(0)=\frac{1}{2} \partial_{i j} \tilde{S}_{g}(0) y^{i} y^{j}+O\left(|y|^{3}\right)
$$

we get for the second term that

$$
\begin{aligned}
\int_{\mathbb{R}^{n}} & \left(\tilde{S}_{g}(y)-\tilde{S}_{g}(0)\right) \tilde{\varphi}(y)^{2^{*}-2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2-n}\left(1+|y|^{2}\right)^{-2} d y \\
= & \frac{1}{2} \partial_{i j} \tilde{S}_{g}(0) \int_{\mathbb{R}^{n}} y^{i} y^{j} \tilde{\varphi}(y)^{2^{*}-2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2-n}\left(1+|y|^{2}\right)^{-2} d y \\
& +O\left(\int_{\mathbb{R}^{n}}|y|^{3}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2-n}\left(1+|y|^{2}\right)^{-2} d y\right) \\
= & -\frac{1}{2 n} \Delta_{\xi} \tilde{S}_{g}(0) \tilde{\varphi}(0)^{2^{*}-2} t_{\alpha}^{n-6} \int_{\mathbb{R}^{n}}|y|^{2}\left(1+|y|^{2}\right)^{2-n} d y+o\left(t_{\alpha}^{n-6}\right)
\end{aligned}
$$

Therefore,
LHS of (2.8)

$$
\begin{aligned}
= & 2^{n} K_{n}^{-1} \omega_{n}^{-\frac{2}{2^{*}}} \varphi\left(x_{0}\right)^{2^{*}-2}\left(\int_{\mathbb{R}^{n}}\left(1+|y|^{2}\right)^{2-n} d y\right)\left(B_{0}(g)-\alpha\right) t_{\alpha}^{-2} \\
- & \frac{2^{n-1}}{n} c_{n} \omega_{n}^{-\frac{2}{2^{*}}} \varphi\left(x_{0}\right)^{2^{*}-2} \Delta_{\xi} \tilde{S}_{g}(0)\left(\int_{\mathbb{R}^{n}}|y|^{2}\left(1+|y|^{2}\right)^{2-n} d y\right) t_{\alpha}^{-4} \\
& +o\left(\left(B_{0}(g)-\alpha\right) t_{\alpha}^{-2}\right)+o\left(t_{\alpha}^{-4}\right)
\end{aligned}
$$

We now deal with the RHS term in (2.8). Through the stereographic projection $\pi_{-x_{\alpha}}$, we get using (1.4) and (1.5), and performing the change of variables $x=t_{\alpha} y$, that

RHS of (2.8)

$$
\begin{aligned}
= & \int_{S^{n}}\left(c_{n} S_{g} \circ \Phi_{\alpha}-\alpha K_{n}^{-1}\right)\left(\varphi \circ \Phi_{\alpha}\right)^{2^{*}-2}\left|\operatorname{det} d \Phi_{\alpha}\right|^{\frac{2}{n}} v_{\alpha}^{2} d v_{h} \\
= & 2^{n} t_{\alpha}^{2-n}\left(c_{n} K_{n} S_{g}\left(x_{\alpha}\right)-\alpha\right) K_{n}^{-1} \int_{\mathbb{R}^{n}} \frac{\tilde{\varphi}_{\alpha}(y)^{2^{*}-2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2}}{\left(1+|y|^{2}\right)^{2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{n-2}} d y \\
& +2^{n} c_{n} t_{\alpha}^{2-n} \int_{\mathbb{R}^{n}} \frac{\left(\tilde{S}_{\alpha}(y)-\tilde{S}_{\alpha}(0)\right) \tilde{\varphi}_{\alpha}(y)^{2^{*}-2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2}}{\left(1+|y|^{2}\right)^{2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{n-2}} d y
\end{aligned}
$$

For any $R>0$,

$$
\int_{\mathbb{R}^{n}} \tilde{\varphi}_{\alpha}(y)^{2^{*}-2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2-n}\left(1+|y|^{2}\right)^{-2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2} d y
$$

$$
\begin{aligned}
& =\omega_{n}^{-\frac{2}{2^{*}}} \int_{B\left(0, R^{-1}\right)} \tilde{\varphi}_{\alpha}(y)^{2^{*}-2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2-n}\left(1+|y|^{2}\right)^{-2} d y \\
& +\int_{B\left(0, R^{-1}\right)} \tilde{\varphi}_{\alpha}(y)^{2^{*}-2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2-n}\left(1+|y|^{2}\right)^{-2}\left(\tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2}-\omega_{n}^{-\frac{2}{2^{*}}}\right) d y \\
& +\int_{\mathbb{R}^{n} \backslash B\left(0, R^{-1}\right)} \tilde{\varphi}_{\alpha}(y)^{2^{*}-2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2-n}\left(1+|y|^{2}\right)^{-2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2} d y
\end{aligned}
$$

Together with (2.6), and letting $R$ go to $+\infty$, this gives

$$
\begin{aligned}
& \int_{\mathbb{R}^{n}} \tilde{\varphi}_{\alpha}(y)^{2^{*}-2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2-n}\left(1+|y|^{2}\right)^{-2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2} d y \\
& =\tilde{\varphi}(0)^{2^{*}-2} \omega_{n}^{-\frac{2}{2^{*}}} t_{\alpha}^{n-4} \int_{\mathbb{R}^{n}}\left(1+|y|^{2}\right)^{2-n} d y+o\left(t_{\alpha}^{n-4}\right)
\end{aligned}
$$

Independently, since $\tilde{v}_{\alpha}$ is bounded (see Theorem 0.3), we get that

$$
\begin{aligned}
\int_{\mathbb{R}^{n}} & \left(\tilde{S}_{\alpha}(y)-\tilde{S}_{\alpha}(0)\right) \tilde{\varphi}_{\alpha}(y)^{2^{*}-2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2-n}\left(1+|y|^{2}\right)^{-2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2} d y \\
= & \partial_{i} \tilde{S}_{\alpha}(0) \int_{\mathbb{R}^{n}} y^{i} \tilde{\varphi}_{\alpha}(y)^{2^{*}-2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2-n}\left(1+|y|^{2}\right)^{-2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2} d y \\
& +\frac{1}{2} \partial_{i j} \tilde{S}_{\alpha}(0) \int_{\mathbb{R}^{n}} y^{i} y^{j} \tilde{\varphi}_{\alpha}(y)^{2^{*}-2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2-n}\left(1+|y|^{2}\right)^{-2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2} d y \\
& +O\left(\int_{\mathbb{R}^{n}}|y|^{3}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2-n}\left(1+|y|^{2}\right)^{-2} d y\right)
\end{aligned}
$$

As above, using (2.6), one easily gets that

$$
\begin{aligned}
& \int_{\mathbb{R}^{n}}\left(\tilde{S}_{\alpha}(y)-\tilde{S}_{\alpha}(0)\right) \tilde{\varphi}_{\alpha}(y)^{2^{*}-2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2-n}\left(1+|y|^{2}\right)^{-2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2} d y \\
& \quad=-\frac{1}{2 n} \omega_{n}^{-\frac{2}{2^{*}}} \tilde{\varphi}(0)^{2^{*}-2} \Delta_{\xi} \tilde{S}_{g}(0)\left(\int_{\mathbb{R}^{n}}|y|^{2}\left(1+|y|^{2}\right)^{2-n} d y\right) t_{\alpha}^{n-6} \\
& \quad+o\left(\left|\nabla S_{g}\left(x_{\alpha}\right)\right| t_{\alpha}^{n-5}\right)+o\left(t_{\alpha}^{n-6}\right)
\end{aligned}
$$

It then follows that
RHS of (2.8)

$$
\begin{aligned}
= & 2^{n} \varphi\left(x_{0}\right)^{2^{*}-2} K_{n}^{-1} \omega_{n}^{-\frac{2}{2^{*}}}\left(\int_{\mathbb{R}^{n}}\left(1+|y|^{2}\right)^{2-n} d y\right)\left(c_{n} K_{n} S_{g}\left(x_{\alpha}\right)-\alpha\right) t_{\alpha}^{-2} \\
& -\frac{2^{n-1}}{n} c_{n} \omega_{n}^{-\frac{2}{2^{*}}} \varphi\left(x_{0}\right)^{2^{*}-2} \Delta_{\xi} \tilde{S}_{g}(0)\left(\int_{\mathbb{R}^{n}}|y|^{2}\left(1+|y|^{2}\right)^{2-n} d y\right) t_{\alpha}^{-4} \\
& +o\left(\left(c_{n} K_{n} S_{g}\left(x_{\alpha}\right)-\alpha\right) t_{\alpha}^{-2}\right)+o\left(t_{\alpha}^{-4}\right)+o\left(\left|\nabla S_{g}\left(x_{\alpha}\right)\right| t_{\alpha}^{-3}\right)
\end{aligned}
$$

Writing that LHS of $(2.8) \leq$ RHS of (2.8), this is just inequality (2.8), we get that

$$
S_{g}\left(x_{0}\right)-S_{g}\left(x_{\alpha}\right) \leq o\left(t_{\alpha}^{-1}\right)\left|\nabla S_{g}\left(x_{\alpha}\right)\right|+o\left(B_{0}(g)-\alpha\right)+o\left(t_{\alpha}^{-2}\right)
$$

By the assumption made in Theorem $0.4, \nabla^{2} S_{g}\left(x_{0}\right)<0$, so that

$$
\begin{aligned}
d_{h}\left(x_{0}, x_{\alpha}\right)^{2} & \leq O\left(S_{g}\left(x_{0}\right)-S_{g}\left(x_{\alpha}\right)\right) \\
& \leq o\left(t_{\alpha}^{-1}\right) d_{h}\left(x_{0}, x_{\alpha}\right)+o\left(B_{0}(g)-\alpha\right)+o\left(t_{\alpha}^{-2}\right)
\end{aligned}
$$

and

$$
d_{h}\left(x_{0}, x_{\alpha}\right)^{2} \leq o\left(B_{0}(g)-\alpha\right)+o\left(t_{\alpha}^{-2}\right)
$$

Summarizing, one gets with (2.8) that

$$
\begin{align*}
& S_{g}\left(x_{0}\right)-S_{g}\left(x_{\alpha}\right) \leq o\left(B_{0}(g)-\alpha\right)+o\left(t_{\alpha}^{-2}\right)  \tag{2.9}\\
& \left|\nabla S_{g}\left(x_{\alpha}\right)\right| \leq o\left(\left(B_{0}(g)-\alpha\right)^{\frac{1}{2}}\right)+o\left(t_{\alpha}^{-1}\right) \tag{2.10}
\end{align*}
$$

We now compute an expansion of the different terms in (2.2). Set $x=t_{\alpha} y$. Since $\tilde{v}_{\alpha}$ is bounded, we get that

$$
\begin{aligned}
I I I_{\alpha}= & t_{\alpha}^{-n}\left(c_{n} \tilde{S}_{\alpha}(0)-\alpha K_{n}^{-1}\right) \int_{\mathbb{R}^{n}} \tilde{\varphi}_{\alpha}(y)^{2^{*}-2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2}|y|^{2} \frac{\left(1+|y|^{2}\right)^{-3}}{\left(t_{\alpha}^{-2}+|y|^{2}\right)^{n-2}} d y \\
& +O\left(t_{\alpha}^{-n}\right) \int_{\mathbb{R}^{n}}|y|^{3}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2-n}\left(1+|y|^{2}\right)^{-3} d y
\end{aligned}
$$

which gives, since $c_{n} \tilde{S}_{\alpha}(0)-\alpha K_{n}^{-1} \rightarrow 0$ as $\alpha \rightarrow B_{0}(g)$,

$$
I I I_{\alpha}=o\left(t_{\alpha}^{-6}\right)
$$

Similarly,

$$
\begin{aligned}
I I_{\alpha}= & K_{n}^{-1}\left(c_{n} K_{n} S_{g}\left(x_{\alpha}\right)-\alpha\right) t_{\alpha}^{-n} \int_{\mathbb{R}^{n}} \frac{\tilde{\varphi}_{\alpha}(y)^{2^{*}-2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2}}{\left(1+|y|^{2}\right)^{3}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{n-2}} d y \\
& +c_{n} t_{\alpha}^{-n} \int_{\mathbb{R}^{n}} \frac{\left(\tilde{S}_{\alpha}(y)-\tilde{S}_{\alpha}(0)\right) \tilde{\varphi}_{\alpha}(y)^{2^{*}-2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2}}{\left(1+|y|^{2}\right)^{3}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{n-2}} d y
\end{aligned}
$$

With (2.6), one sees with the same kind of arguments than those used above that

$$
\begin{aligned}
& \int_{\mathbb{R}^{n}} \tilde{\varphi}_{\alpha}(y)^{2^{*}-2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2-n}\left(1+|y|^{2}\right)^{-3} d y \\
& \quad=\varphi\left(x_{0}\right)^{2^{*}-2} \omega_{n}^{-\frac{2}{2^{*}}}\left(\int_{\mathbb{R}^{n}}\left(1+|y|^{2}\right)^{2-n} d y\right) t_{\alpha}^{n-4}+o\left(t_{\alpha}^{n-4}\right)
\end{aligned}
$$

On the other hand, we write with (2.10)
$\tilde{S}_{\alpha}(y)-\tilde{S}_{\alpha}(0)=o\left(\left(B_{0}(g)-\alpha\right)^{\frac{1}{2}}\right)|y|+o\left(t_{\alpha}^{-1}\right)|y|+\frac{1}{2} \partial_{i j} \tilde{S}_{\alpha}(0) y^{i} y^{j}+O\left(|y|^{3}\right)$
This gives, after some computations similar to the ones we developed above, that

$$
\begin{aligned}
& \int_{\mathbb{R}^{n}}\left(\tilde{S}_{\alpha}(y)-\tilde{S}_{\alpha}(0)\right) \tilde{\varphi}_{\alpha}(y)^{2^{*}-2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2-n}\left(1+|y|^{2}\right)^{-3} d y \\
& \quad=-\frac{1}{2 n} \varphi\left(x_{0}\right)^{2^{*}-2} \omega_{n}^{-\frac{2}{2^{*}}} \Delta_{\xi} \tilde{S}_{g}(0)\left(\int_{\mathbb{R}^{n}}|y|^{2}\left(1+|y|^{2}\right)^{2-n} d y\right) t_{\alpha}^{n-6} \\
& \quad+o\left(t_{\alpha}^{n-6}\right)+o\left(\left(B_{0}(g)-\alpha\right)^{\frac{1}{2}} t_{\alpha}^{n-5}\right)
\end{aligned}
$$

Noting that

$$
o\left(\left(B_{0}(g)-\alpha\right)^{\frac{1}{2}} t_{\alpha}^{n-5}\right)=o\left(\left(B_{0}(g)-\alpha\right) t_{\alpha}^{n-4}\right)+o\left(t_{\alpha}^{n-6}\right)
$$

we therefore get with (2.9) that

$$
\begin{aligned}
I I_{\alpha}= & \varphi\left(x_{0}\right)^{2^{*}-2} K_{n}^{-1} \omega_{n}^{-\frac{2}{2^{*}}}\left(\int_{\mathbb{R}^{n}}\left(1+|y|^{2}\right)^{2-n} d y\right)\left(B_{0}(g)-\alpha\right) t_{\alpha}^{-4} \\
& -\frac{c_{n}}{2 n} \varphi\left(x_{0}\right)^{2^{*}-2} \omega_{n}^{-\frac{2}{2^{*}}} \Delta_{\xi} \tilde{S}_{g}(0)\left(\int_{\mathbb{R}^{n}}|y|^{2}\left(1+|y|^{2}\right)^{2-n} d y\right) t_{\alpha}^{-6} \\
& +o\left(t_{\alpha}^{-6}\right)+o\left(\left(B_{0}(g)-\alpha\right) t_{\alpha}^{-4}\right)
\end{aligned}
$$

At last, we deal with $I_{\alpha}$. We have here

$$
I_{\alpha}=\frac{t_{\alpha}^{-n}}{2} \int_{\mathbb{R}^{n}} \frac{\left(\nabla\left[\left(c_{n} \tilde{S}_{\alpha}(y)-\alpha K_{n}^{-1}\right) \tilde{\varphi}_{\alpha}(y)^{2^{*}-2}\right], y\right) \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2}}{\left(t_{\alpha}^{-2}+|y|^{2}\right)^{n-2}\left(1+|y|^{2}\right)^{2}} d y
$$

From (2.10), we deduce that

$$
\begin{aligned}
& \left(\nabla\left[\left(c_{n} \tilde{S}_{\alpha}(y)-\alpha K_{n}^{-1}\right) \tilde{\varphi}_{\alpha}(y)^{2^{*}-2}\right], y\right) \\
& =c_{n} \tilde{\varphi}_{\alpha}(0)^{2^{*}-2} \partial_{i j} \tilde{S}_{\alpha}(0) y^{i} y^{j}+o\left(\left(B_{0}(g)-\alpha\right)^{\frac{1}{2}}\right)|y|+o\left(t_{\alpha}^{-1}\right)|y| \\
& \quad+o\left(\left(B_{0}(g)-\alpha\right)^{\frac{1}{2}}\right)|y|^{2}+o\left(t_{\alpha}^{-1}\right)|y|^{2}+O\left(|y|^{3}\right)
\end{aligned}
$$

This gives :

$$
\begin{aligned}
I_{\alpha} & =-\frac{c_{n}}{2 n} \varphi\left(x_{0}\right)^{2^{*}-2} \omega_{n}^{-\frac{2}{2^{*}}} \Delta_{\xi} \tilde{S}_{g}(0)\left(\int_{\mathbb{R}^{n}}|y|^{2}\left(1+|y|^{2}\right)^{2-n} d y\right) t_{\alpha}^{-6} \\
& +o\left(t_{\alpha}^{-6}\right)+o\left(\left(B_{0}(g)-\alpha\right) t_{\alpha}^{-4}\right)
\end{aligned}
$$

By letting $\alpha$ go to $B_{0}(g)$ in (2.2), we obtain

$$
\lim _{\alpha \rightarrow B_{0}(g)}\left(B_{0}(g)-\alpha\right) t_{\alpha}^{2}=\frac{c_{n} K_{n}}{n} \Delta_{\xi} \tilde{S}_{g}(0) \frac{\int_{\mathbb{R}^{n}}|y|^{2}\left(1+|y|^{2}\right)^{2-n} d y}{\int_{\mathbb{R}^{n}}\left(1+|y|^{2}\right)^{2-n} d y}
$$

Easy computations lead then to

$$
\Delta_{\xi} \tilde{S}_{g}(0)=4 \varphi\left(x_{0}\right)^{2^{*}-2} \Delta_{g} S_{g}\left(x_{0}\right)
$$

and

$$
\frac{c_{n} K_{n}}{n} \frac{\int_{\mathbb{R}^{n}}|y|^{2}\left(1+|y|^{2}\right)^{2-n} d y}{\int_{\mathbb{R}^{n}}\left(1+|y|^{2}\right)^{2-n} d y}=\frac{\omega_{n}^{-\frac{2}{n}}}{n(n-1)(n-6)}
$$

Hence,

$$
\lim _{\alpha \rightarrow B_{0}(g)}\left(B_{0}(g)-\alpha\right) t_{\alpha}^{2}=\frac{4 \omega_{n}^{-\frac{2}{n}}}{n(n-1)(n-6)} \varphi\left(x_{0}\right)^{2^{*}-2} \Delta_{g} S_{g}\left(x_{0}\right)
$$

and the first part of Theorem 0.4 is proved when $n \geq 7$. To prove the second part, just note that by (2.9),

$$
d_{h}\left(x_{0}, x_{\alpha}\right)=o\left(t_{\alpha}^{-1}\right)
$$

As easily seen, this allows us to replace $x_{\alpha}$ by $x_{0}$ in the proof of Theorem 0.3.

In order to end this subsection, we list the different results we obtain in dimension $n=6$ when computing the LHS and RHS terms of (2.8), and the different terms of (2.2). The details are left to the reader. Only few changes are needed with respect to the case $n \geq 7$. We obtain

LHS of (2.8)

$$
\begin{aligned}
= & 2^{6} K_{6}^{-1} \omega_{6}^{-\frac{2}{3}} \varphi\left(x_{0}\right)\left(\int_{\mathbb{R}^{6}}\left(1+|y|^{2}\right)^{-4} d y\right)\left(B_{0}(g)-\alpha\right) t_{\alpha}^{-2} \\
& -\frac{2^{4}}{3} c_{6} \omega_{6}^{-\frac{2}{3}} \omega_{5} \varphi\left(x_{0}\right) \Delta_{\xi} \tilde{S}_{g}(0) t_{\alpha}^{-4} \ln t_{\alpha} \\
& +o\left(t_{\alpha}^{-4} \ln t_{\alpha}\right)+o\left(\left(B_{0}(g)-\alpha\right) t_{\alpha}^{-2}\right)
\end{aligned}
$$

and
RHS of (2.8)

$$
\begin{aligned}
= & 2^{6} K_{6}^{-1} \omega_{6}^{-\frac{2}{3}} \varphi\left(x_{0}\right)\left(\int_{\mathbb{R}^{6}}\left(1+|y|^{2}\right)^{-4} d y\right)\left(c_{6} K_{6} S_{g}\left(x_{\alpha}\right)-\alpha\right) t_{\alpha}^{-2} \\
& +o\left(\left(c_{6} K_{6} S_{g}\left(x_{\alpha}\right)-\alpha\right) t_{\alpha}^{-2}\right)-\frac{2^{4}}{3} c_{6} \omega_{6}^{-\frac{2}{3}} \omega_{5} \varphi\left(x_{0}\right) \Delta_{\xi} \tilde{S}_{g}(0) t_{\alpha}^{-4} \ln t_{\alpha} \\
& +o\left(t_{\alpha}^{-4} \ln t_{\alpha}\right)+o\left(\left|\nabla S_{g}\left(x_{\alpha}\right)\right| t_{\alpha}^{-3}\right)
\end{aligned}
$$

Together with (2.8), this gives

$$
\begin{aligned}
& S_{g}\left(x_{0}\right)-S_{g}\left(x_{\alpha}\right) \leq o\left(B_{0}(g)-\alpha\right)+o\left(t_{\alpha}^{-2} \ln t_{\alpha}\right) \\
& \left|\nabla S_{g}\left(x_{\alpha}\right)\right| \leq o\left(\left(B_{0}(g)-\alpha\right)^{\frac{1}{2}}\right)+o\left(t_{\alpha}^{-1}\left(\ln t_{\alpha}\right)^{\frac{1}{2}}\right)
\end{aligned}
$$

As for (2.2), using these estimates, we get

$$
\begin{aligned}
& I_{\alpha}=-\frac{c_{6}}{12} \varphi\left(x_{0}\right) \omega_{6}^{-\frac{2}{3}} \omega_{5} \Delta_{\xi} \tilde{S}_{g}(0) t_{\alpha}^{-6} \ln t_{\alpha}+o\left(t_{\alpha}^{-6} \ln t_{\alpha}\right)+o\left(\left(B_{0}(g)-\alpha\right) t_{\alpha}^{-4}\right) \\
& I I_{\alpha}= \varphi\left(x_{0}\right) K_{6}^{-1} \omega_{6}^{-\frac{2}{3}}\left(\int_{\mathbb{R} R^{6}}\left(1+|y|^{2}\right)^{-4} d y\right)\left(B_{0}(g)-\alpha\right) t_{\alpha}^{-4} \\
&-\frac{c_{6}}{12} \varphi\left(x_{0}\right) \omega_{6}^{-\frac{2}{3}} \omega_{5} \Delta_{\xi} \tilde{S}_{g}(0) t_{\alpha}^{-6} \ln t_{\alpha} \\
&+o\left(t_{\alpha}^{-6} \ln t_{\alpha}\right)+o\left(\left(B_{0}(g)-\alpha\right) t_{\alpha}^{-4}\right)
\end{aligned}
$$

and

$$
I I I_{\alpha}=o\left(t_{\alpha}^{-6} \ln t_{\alpha}\right)
$$

Letting $\alpha$ go to $B_{0}(g)$ in (2.2), we therefore get that

$$
\lim _{\alpha \rightarrow B_{0}(g)}\left(B_{0}(g)-\alpha\right) t_{\alpha}^{2}\left(\ln t_{\alpha}\right)^{-1}=\frac{2}{15} \omega_{6}^{-\frac{1}{3}} \varphi\left(x_{0}\right) \Delta_{g} S_{g}\left(x_{0}\right)
$$

This proves Theorem 0.4 when $n=6$.

## 2.2 - The case $n=4,5$

We prove now Theorem 0.4 when $n=4,5$. As a starting point, we need a substitute for (2.8) in order to get informations on the speed of convergence of $x_{\alpha}$ to $x_{0}$. We note here that
$\Delta_{\xi}\left(\tilde{v}_{\alpha} \psi\right)=$

$$
\left[\lambda_{\alpha}+\left(c_{n} \tilde{S}_{\alpha}\left(\frac{x}{t_{\alpha}}\right)-\alpha K_{n}^{-1}\right) t_{\alpha}^{2} \frac{\left(1+|x|^{2}\right)^{2}}{\left(t_{\alpha}^{2}+|x|^{2}\right)^{2}} \tilde{\varphi}_{\alpha}\left(\frac{x}{t_{\alpha}}\right)^{2^{*}-2} \tilde{v}_{\alpha}^{2-2^{*}}\right]\left(\tilde{v}_{\alpha} \psi\right)^{2^{*}-1}
$$

where $\psi=\left(\frac{1+|x|^{2}}{2}\right)^{1-\frac{n}{2}}$. Integrations by parts then give that

$$
\begin{align*}
& \int_{\mathbb{R}^{n}} \frac{\tilde{v}_{\alpha}\left(t_{\alpha} x\right)^{2}}{\left(t_{\alpha}^{-2}+|x|^{2}\right)^{n-2}\left(1+|x|^{2}\right)^{2}} \nabla\left[\left(c_{n} \tilde{S}_{\alpha}(x)-\alpha K_{n}^{-1}\right) \tilde{\varphi}_{\alpha}(x)^{2^{*}-2}\right] d x \\
& \quad=4 \int_{\mathbb{R}^{n}} \frac{\left(c_{n} \tilde{S}_{\alpha}(x)-\alpha K_{n}^{-1}\right) \tilde{\varphi}_{\alpha}(x)^{2^{*}-2} \tilde{v}_{\alpha}\left(t_{\alpha} x\right)^{2}}{\left(t_{\alpha}^{-2}+|x|^{2}\right)^{n-2}\left(1+|x|^{2}\right)^{3}} x d x \tag{2.11}
\end{align*}
$$

We assume now that $n=4$, and refer to the end of this subsection for the case where $n=5$. Together with Lebesgue's theorem, with the fact that ( $\tilde{v}_{\alpha}$ ) is bounded and with (2.5), (2.11) gives that

$$
\begin{aligned}
& c_{4} \omega_{4}^{-\frac{1}{2}} \int_{\mathbb{R}^{4}} \nabla\left[\left(\tilde{S}_{g}(x)-\tilde{S}_{g}(0)\right) \tilde{\varphi}(x)^{2}\right] \frac{\left[1+|x|^{2}\left(1+|x|^{2}\right)^{-1} \tilde{\sigma}(x)\right]}{|x|^{4}\left(1+|x|^{2}\right)^{2}} d x \\
& +\nabla\left[\left(c_{4} \tilde{S}_{\alpha}(x)-\alpha K_{4}^{-1}\right) \tilde{\varphi}_{\alpha}(x)^{2}\right](0) \int_{\mathbb{R}^{4}} \frac{\tilde{v}_{\alpha}\left(t_{\alpha} x\right)^{2}}{\left(1+|x|^{2}\right)^{2}\left(t_{\alpha}^{-2}+|x|^{2}\right)^{2}} d x+o(1) \\
& =4 c_{4} \omega_{4}^{-\frac{1}{2}} \int_{\mathbb{R}^{4}}\left(\tilde{S}_{g}(x)-\tilde{S}_{g}(0)\right) \tilde{\varphi}(x)^{2} \frac{\left[1+|x|^{2}\left(1+|x|^{2}\right)^{-1} \tilde{\sigma}(x)\right]}{|x|^{4}\left(1+|x|^{2}\right)^{3}} x d x
\end{aligned}
$$

Together with (2.6), we get that

$$
\int_{\mathbb{R}^{4}} \tilde{v}_{\alpha}\left(t_{\alpha} x\right)^{2}\left(t_{\alpha}^{-2}+|x|^{2}\right)^{-2}\left(1+|x|^{2}\right)^{-2} d x=\omega_{4}^{-\frac{1}{2}} \omega_{3} \ln t_{\alpha}+o\left(\ln t_{\alpha}\right)
$$

Therefore,

$$
\begin{equation*}
\left|\nabla\left[\left(c_{4} \tilde{S}_{\alpha}(x)-\alpha K_{4}^{-1}\right) \tilde{\varphi}_{\alpha}(x)^{2}\right](0)\right|=O\left(\left(\ln t_{\alpha}\right)^{-1}\right) \tag{2.12}
\end{equation*}
$$

We now compute the different terms in (2.2). Setting $x=t_{\alpha} y$, and by Lebesgue's theorem, we get that

$$
\begin{aligned}
I I I_{\alpha}= & t_{\alpha}^{-4} \int_{\mathbb{R}^{4}}\left(c_{4} \tilde{S}_{\alpha}(y)-\alpha K_{4}^{-1}\right) \tilde{\varphi}_{\alpha}(y)^{2} \frac{|y|^{2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2}}{\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2}\left(1+|y|^{2}\right)^{3}} d y \\
= & c_{4} \omega_{4}^{-\frac{1}{2}} t_{\alpha}^{-4} \int_{\mathbb{R}^{4}}\left(\tilde{S}_{g}(y)-\tilde{S}_{g}(0)\right) \tilde{\varphi}(y)^{2} \frac{\left[1+|y|^{2}\left(1+|y|^{2}\right)^{-1} \tilde{\sigma}(y)\right]^{2}}{|y|^{2}\left(1+|y|^{2}\right)^{3}} d y \\
& +o\left(t_{\alpha}^{-4}\right)
\end{aligned}
$$

Performing the same change of variables in $I I_{\alpha}$, we get that

$$
\begin{aligned}
I I_{\alpha}= & t_{\alpha}^{-4} K_{4}^{-1}\left(c_{4} S_{g}\left(x_{\alpha}\right) K_{4}-\alpha\right) \int_{\mathbb{R}^{4}} \frac{\tilde{\varphi}_{\alpha}(y)^{2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2}}{\left(1+|y|^{2}\right)^{3}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2}} d y \\
& +c_{4} t_{\alpha}^{-4} \int_{\mathbb{R}^{4}} \frac{\left(\tilde{S}_{\alpha}(y)-\tilde{S}_{\alpha}(0)\right) \tilde{\varphi}_{\alpha}(y)^{2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2}}{\left(1+|y|^{2}\right)^{3}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{2}} d y
\end{aligned}
$$

Since

$$
\left|\tilde{S}_{\alpha}(y)-\tilde{S}_{\alpha}(0)\right| \leq C|y|
$$

the integral in the second term of the RHS of this relation converges. For the first term in the RHS of this relation, (2.6), together with the same trick than we used in subsection 2.1, gives that

$$
\begin{aligned}
\int_{\mathbb{R}^{4}} & \tilde{\varphi}_{\alpha}(y)^{2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{-2}\left(1+|y|^{2}\right)^{-3} d y \\
& =\varphi\left(x_{0}\right)^{2} \omega_{4}^{-\frac{1}{2}} \omega_{3} \ln t_{\alpha}+o\left(\ln t_{\alpha}\right)
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
I I_{\alpha}= & K_{4}^{-1} \varphi\left(x_{0}\right)^{2} \omega_{4}^{-\frac{1}{2}} \omega_{3}\left(c_{4} S_{g}\left(x_{\alpha}\right) K_{4}-\alpha\right) t_{\alpha}^{-4} \ln t_{\alpha} \\
& +o\left(\left(c_{4} S_{g}\left(x_{\alpha}\right) K_{4}-\alpha\right) t_{\alpha}^{-4} \ln t_{\alpha}\right)+o\left(t_{\alpha}^{-4}\right) \\
& +c_{4} \omega_{4}^{-\frac{1}{2}} t_{\alpha}^{-4} \int_{\mathbb{R}^{4}}\left(\tilde{S}_{g}(y)-\tilde{S}_{g}(0)\right) \tilde{\varphi}(y)^{2} \frac{\left[1+|y|^{2}\left(1+|y|^{2}\right)^{-1} \tilde{\sigma}(y)\right]^{2}}{|y|^{4}\left(1+|y|^{2}\right)^{3}} d y
\end{aligned}
$$

Similar computations give that

$$
\begin{aligned}
I_{\alpha}=\frac{c_{4}}{2} \omega_{4}^{-\frac{1}{2}} t_{\alpha}^{-4} & \int_{\mathbb{R}^{4}}\left(\nabla\left[\left(\tilde{S}_{g}(y)-\tilde{S}_{g}(0)\right) \tilde{\varphi}(y)^{2}\right], y\right) \\
& \times \frac{\left[1+|y|^{2}\left(1+|y|^{2}\right)^{-1} \tilde{\sigma}(y)\right]^{2}}{\left(1+|y|^{2}\right)^{2}|y|^{4}} d y+o\left(t_{\alpha}^{-4}\right)
\end{aligned}
$$

Coming back to (2.2), and passing to the limit $\alpha \rightarrow B_{0}(g)$ in this relation, we obtain

$$
\begin{aligned}
& \lim _{\alpha \rightarrow B_{0}(g)}\left(c_{4} S_{g}\left(x_{\alpha}\right) K_{4}-\alpha\right) \ln t_{\alpha} \\
& =\frac{\varphi\left(x_{0}\right)^{-2}}{24 \omega_{3}} \omega_{4}^{-\frac{1}{2}}
\end{aligned}
$$

$$
\begin{aligned}
& \times {\left[2 \int_{\mathbb{R}^{4}}\left(\tilde{S}_{g}(y)-\tilde{S}_{g}(0)\right) \tilde{\varphi}(y)^{2} \frac{\left(|y|^{2}-1\right)\left[|y|^{-2}\left(1+|y|^{2}\right)+\tilde{\sigma}(y)\right]^{2}}{\left(1+|y|^{2}\right)^{5}} d y\right.} \\
&\left.\quad-\int_{\mathbb{R}^{4}}\left(\nabla\left[\left(\tilde{S}_{g}(y)-\tilde{S}_{g}(0)\right) \tilde{\varphi}(y)^{2}\right], y\right) \frac{\left[|y|^{-2}\left(1+|y|^{2}\right)+\tilde{\sigma}(y)\right]^{2}}{\left(1+|y|^{2}\right)^{4}} d y\right]
\end{aligned}
$$

We use (2.12) to conclude. By (2.12),

$$
\left|\nabla \tilde{S}_{\alpha}(0)\right|=O\left(\left(\ln t_{\alpha}\right)^{-1}\right)
$$

so that, together with the assumption $\nabla^{2} S_{g}\left(x_{0}\right)<0$ we made in Theorem 0.4 ,

$$
d_{h}\left(x_{0}, x_{\alpha}\right)=O\left(\left(\ln t_{\alpha}\right)^{-1}\right)
$$

and

$$
S_{g}\left(x_{0}\right)-S_{g}\left(x_{\alpha}\right)=o\left(\left(\ln t_{\alpha}\right)^{-1}\right)
$$

Hence,

$$
\begin{align*}
& \lim _{\alpha \rightarrow B_{0}(g)}\left(B_{0}(g)-\alpha\right) \ln t_{\alpha} \\
&= \frac{\varphi\left(x_{0}\right)^{-2}}{4 \omega_{3}} \omega_{4}^{-\frac{1}{2}}  \tag{2.13}\\
& \times {\left[2 c_{4} \int_{\mathbb{R}^{4}}\left(\tilde{S}_{g}(y)-\tilde{S}_{g}(0)\right) \tilde{\varphi}(y)^{2} \frac{\left(|y|^{2}-1\right)\left[|y|^{-2}\left(1+\left.|y|\right|^{2}\right)+\tilde{\sigma}(y)\right]^{2}}{\left(1+|y|^{2}\right)^{5}} d y\right.} \\
&\left.\quad-c_{4} \int_{\mathbb{R}^{4}}\left(\nabla\left[\left(\tilde{S}_{g}(y)-\tilde{S}_{g}(0)\right) \tilde{\varphi}(y)^{2}\right], y\right) \frac{\left[|y|^{-2}\left(1+|y|^{2}\right)+\tilde{\sigma}(y)\right]^{2}}{\left(1+|y|^{2}\right)^{4}} d y\right]
\end{align*}
$$

In order to simplify this expression, we let

$$
\psi(y)=2\left(1+|y|^{2}\right)^{-1}
$$

so that $\left(\pi_{-x_{0}}^{-1}\right)^{*} h=\psi^{2} \xi$. By (2.4), we have :

$$
\Delta_{\xi}(\psi \tilde{\sigma})=c_{4}\left(\tilde{S}_{g}(y)-\tilde{S}_{g}(0)\right) \tilde{\varphi}^{2} \psi^{2}\left[2|y|^{-2}+\tilde{\sigma} \psi\right]
$$

Regarding the first integral in the RHS term of (2.13), we write that

$$
\begin{aligned}
& 2 c_{4} \int_{\mathbb{R}^{4}}\left(\tilde{S}_{g}(y)-\tilde{S}_{g}(0)\right) \tilde{\varphi}(y)^{2} \frac{\left(|y|^{2}-1\right)}{\left(1+|y|^{2}\right)^{5}}\left[|y|^{-2}\left(1+|y|^{2}\right)+\tilde{\sigma}(y)\right]^{2} d y \\
& \quad=2^{-4} \int_{\mathbb{R}^{4}} \Delta_{\xi}(\psi \tilde{\sigma})(y)\left[2|y|^{-2}+\tilde{\sigma}(y) \psi(y)\right] \psi(y)\left(|y|^{2}-1\right) d y
\end{aligned}
$$

As for the second one, integrations by parts give that

$$
\begin{aligned}
& -c_{4} \int_{\mathbb{R}^{4}}\left(\nabla\left[\left(\tilde{S}_{g}(y)-\tilde{S}_{g}(0)\right) \tilde{\varphi}(y)^{2}\right], y\right) \frac{\left[|y|^{-2}\left(1+|y|^{2}\right)+\tilde{\sigma}(y)\right]^{2}}{\left(1+|y|^{2}\right)^{4}} d y \\
& =2^{-4} \times 4 \int_{\mathbb{R}^{4}} \Delta_{\xi}(\psi \tilde{\sigma})(y)\left[2|y|^{-2}+\tilde{\sigma}(y) \psi(y)\right] d y \\
& \quad+2^{-3} \int_{\mathbb{R}^{4}} \Delta_{\xi}(\psi \tilde{\sigma})(y) \psi(y)^{-1}\left(\nabla\left(\left[2|y|^{-2}+\tilde{\sigma}(y) \psi(y)\right] \psi(y)\right), y\right) d y
\end{aligned}
$$

Some more integrations by parts then lead to

$$
\text { RHS of }(2.13)=-\frac{\varphi\left(x_{0}\right)^{-2}}{16 \omega_{3}} \omega_{4}^{-\frac{1}{2}} \int_{\mathbb{R}^{4}} \Delta_{\xi}(\psi \tilde{\sigma})(y)|y|^{-2} d y
$$

Since

$$
\Delta_{\xi}\left(|y|^{-2}\right)=2 \omega_{3} \delta_{0}
$$

it follows that

$$
\lim _{\alpha \rightarrow B_{0}(g)}\left(B_{0}(g)-\alpha\right) \ln t_{\alpha}=-\frac{1}{4} \omega_{4}^{-\frac{1}{2}} \varphi\left(x_{0}\right)^{-2} \sigma\left(x_{0}\right)
$$

Note here that $\sigma\left(x_{0}\right)$ makes sense, since for $n=4, \sigma \in C^{0}\left(S^{4}\right)$. By the Green's formula on ( $S^{n}, h$ ), together with (2.4) and (2.3),

$$
\begin{aligned}
\sigma\left(x_{0}\right) & =\frac{1}{8 \omega_{3}} \int_{S^{4}} L_{h} \sigma(x)\left(\frac{1-\left(x_{0}, x\right)}{2}\right)^{-1} d v_{h} \\
& =\frac{1}{6} \varphi\left(x_{0}\right) \int_{S^{4}}\left(S_{g}(x)-S_{g}\left(x_{0}\right)\right) \varphi(x)^{-1}\left(\frac{1-\left(x_{0}, x\right)}{2}\right)^{-1} G\left(x_{0}, x\right) d v_{g}
\end{aligned}
$$

This proves Theorem 0.4 when $n=4$.
When $n=5$, similar computations lead to

$$
\begin{aligned}
& I_{\alpha}=\frac{1}{2} c_{5} \omega_{5}^{-\frac{2}{2^{*} t}} t_{\alpha}^{-5} \int_{\mathbb{R}^{5}}\left(\nabla\left[\left(\tilde{S}_{g}(y)-\tilde{S}_{g}(0)\right) \tilde{\varphi}(y)^{2^{*}-2}\right], y\right) \\
& \times \frac{\left(|y|^{-3}\left(1+|y|^{2}\right)^{\frac{3}{2}}+\tilde{\sigma}(y)\right)^{2}}{\left(1+|y|^{2}\right)^{5}} d y \\
&+o\left(t_{\alpha}^{-5}\right)+o\left(\left(B_{0}(g)-\alpha\right) t_{\alpha}^{-4}\right),
\end{aligned}
$$

$$
\begin{aligned}
& I I_{\alpha}=K_{5}^{-1} \omega_{5}^{-\frac{2}{2^{*}}} \varphi\left(x_{0}\right)^{2^{*}-2}\left(\int_{\mathbb{R}^{5}}\left(1+|y|^{2}\right)^{-3} d y\right)\left(B_{0}(g)-\alpha\right) t_{\alpha}^{-4} \\
& +o\left(\left(B_{0}(g)-\alpha\right) t_{\alpha}^{-4}\right)+o\left(t_{\alpha}^{-5}\right) \\
& +c_{5} \omega_{5}^{-\frac{2}{2^{*}}} t_{\alpha}^{-5} \int_{\mathbb{R}^{5}}\left(\tilde{S}_{g}(y)-\tilde{S}_{g}(0)\right) \tilde{\varphi}(y)^{2^{*}-2} \frac{\left[|y|^{-3}\left(1+|y|^{2}\right)^{\frac{3}{2}}+\tilde{\sigma}(y)\right]^{2}}{\left(1+|y|^{2}\right)^{6}} d y
\end{aligned}
$$

and

$$
\begin{aligned}
I I I_{\alpha}= & c_{5} \omega_{5}^{-\frac{2}{2^{*}}} t_{\alpha}^{-5} \\
& \times \int_{\mathbb{R}^{5}}\left(\tilde{S}_{g}(y)-\tilde{S}_{g}(0)\right) \tilde{\varphi}(y)^{2^{*}-2}|y|^{2} \frac{\left[|y|^{-3}\left(1+|y|^{2}\right)^{\frac{3}{2}}+\tilde{\sigma}(y)\right]^{2}}{\left(1+|y|^{2}\right)^{6}} d y \\
& +o\left(t_{\alpha}^{-5}\right)
\end{aligned}
$$

Coming back to (2.2), and letting $\alpha$ go to $B_{0}(g)$, we get that

$$
\begin{aligned}
& \lim _{\alpha \rightarrow B_{0}(g)}\left(B_{0}(g)-\alpha\right) t_{\alpha}=\frac{3}{10 \pi} \omega_{5}^{-\frac{3}{5}} \varphi\left(x_{0}\right)^{-\frac{1}{3}} \\
& \quad \times \int_{S^{5}}\left(S_{g}\left(x_{0}\right)-S_{g}(x)\right) \varphi(x)^{-1}\left(\frac{1-\left(x_{0}, x\right)}{2}\right)^{-\frac{3}{2}} G\left(x_{0}, x\right) d v_{g}
\end{aligned}
$$

This ends the proof of Theorem 0.4.

## 3 - The radial case : proof of Theorem 0.5

Let $x_{0} \in S^{n}$, and $g=\varphi^{\frac{4}{n-2}} h$, where $\varphi$ is radially symmetrical with respect to $x_{0}$. Clearly, $S_{g}$ is also radially symmetrical with respect to $x_{0}$. We assume in what follows that for any $\lambda>0, g$ and $\lambda h$ are not isometric. We then define

$$
B_{0}(g)_{r}=\inf \left\{B>0 \text { s.t. }\left(I_{o p t}\right) \text { is valid with } B \text { for any } u \in C_{r}^{\infty}\left(S^{n}\right)\right\}
$$

where $C_{r}^{\infty}\left(S^{n}\right)$ is the set of functions in $C^{\infty}\left(S^{n}\right)$ which are radially symmetrical with respect to $x_{0}$. We have $B_{0}(g)_{r} \leq B_{0}(g)=c_{n} K_{n} \max _{S^{n}} S_{g}$, while, using test functions as in Hebey [16],

$$
B_{0}(g)_{r} \geq c_{n} K_{n} \max _{\left\{x_{0},-x_{0}\right\}} S_{g}
$$

Assume now that

$$
\max _{\left\{x_{0},-x_{0}\right\}} S_{g}=\max _{S^{n}} S_{g}=S_{g}\left(x_{0}\right)
$$

Then

$$
B_{0}(g)_{r}=B_{0}(g)=c_{n} K_{n} \max _{S^{n}} S_{g}
$$

As easily seen, it follows that we can choose the sub-extremals $\left(z_{\alpha}\right)$ to be radially symmetrical with respect to $x_{0}$. If $x_{1}$ is the concentration point of $\left(z_{\alpha}\right)$, we know (see for instance Hebey [14]) that $x_{1} \in\left\{x_{0},-x_{0}\right\}$. Moreover, see section $1, x_{1}$ has to be a point where $S_{g}$ is maximum. Without loss of generality, we may then assume that $x_{1}=x_{0}$.

We let now $x_{\alpha}$ be as in section 1, and claim that

$$
\begin{equation*}
d_{h}\left(x_{0}, x_{\alpha}\right)=o\left(t_{\alpha}^{-1}\right) \tag{3.1}
\end{equation*}
$$

To prove this claim, let $\pi_{-x_{0}}$ be the stereographic projection of north pole $-x_{0}$. Since $u_{\alpha}=z_{\alpha} \varphi$ is radially symmetrical with respect to $x_{0}$, we get that for any $k \in I N$ and any $i=1, \ldots, n$

$$
\int_{S_{+}^{n}} \pi_{-x_{0}}^{i}(x) u_{\alpha}^{k} d v_{h}=0
$$

where $S_{+}^{n}=B\left(x_{0}, \frac{\pi}{2}\right)$. Hence,

$$
\int_{S_{+}^{n}} \pi_{-x_{0}}^{i}\left(\Phi_{\alpha}(x)\right) v_{\alpha}^{k}\left|\operatorname{det} d \Phi_{\alpha}\right|^{1-\frac{k}{2^{*}}} d v_{h}=0
$$

We let

$$
\tilde{v}_{\alpha}=v_{\alpha} \circ \pi_{-x_{\alpha}}^{-1}
$$

so that, by (1.4) and (1.5),

$$
\int_{\pi_{-x_{\alpha}}\left(S_{+}^{n}\right)} \pi_{-x_{0}}^{i}\left(\pi_{-x_{\alpha}}^{-1}\left(\frac{x}{t_{\alpha}}\right)\right) \tilde{v}_{\alpha}(x)^{k} \frac{\left(1+t_{\alpha}^{-2}|x|^{2}\right)^{-n\left(1-\frac{k}{2^{*}}\right)}}{\left(1+|x|^{2}\right)^{\frac{k n}{2^{*}}}} d x=0
$$

Performing the change of variables $x=t_{\alpha} y$, we obtain

$$
\int_{\pi_{-x_{\alpha}}\left(S_{+}^{n}\right)} \pi_{-x_{0}}^{i}\left(\pi_{-x_{\alpha}}^{-1}(y)\right) \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{k}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{-\frac{k n}{2^{*}}}\left(1+|y|^{2}\right)^{-n\left(1-\frac{k}{2^{*}}\right)} d y=0
$$

We have that for any $y \in \pi_{-x_{\alpha}}\left(S_{+}^{n}\right)$,

$$
\pi_{-x_{0}}^{i}\left(\pi_{-x_{\alpha}}^{-1}(y)\right)=\pi_{-x_{0}}^{i}\left(x_{\alpha}\right)+C(\alpha)_{i j} y^{j}+O\left(|y|^{2}\right)
$$

where the $C(\alpha)_{i j}$ 's are bounded. This leads to

$$
\begin{aligned}
& \pi_{-x_{0}}^{i}\left(x_{\alpha}\right) \int_{\pi_{-x_{\alpha}}\left(S_{+}^{n}\right)} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{k}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{-\frac{k n}{2^{*}}}\left(1+|y|^{2}\right)^{-n\left(1-\frac{k}{2^{* *}}\right)} d y \\
& \quad=-C(\alpha)_{i j} \int_{\pi_{-x_{\alpha}}\left(S_{+}^{n}\right)} y^{j} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{k}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{-\frac{k n}{2^{*}}}\left(1+|y|^{2}\right)^{-n\left(1-\frac{k}{2^{*}}\right)} d y \\
& \quad+O\left(\int_{\pi_{-x_{\alpha}}\left(S_{+}^{n}\right)}|y|^{2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{k}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{-\frac{k n}{2^{*}}}\left(1+|y|^{2}\right)^{-n\left(1-\frac{k}{2^{*}}\right)} d y\right)
\end{aligned}
$$

When $2^{*}>k>\frac{n+2}{n-2}$,

$$
\begin{aligned}
& \int_{\pi_{-x_{\alpha}}\left(S_{+}^{n}\right)} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{k}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{-\frac{k n}{2^{*}}}\left(1+|y|^{2}\right)^{-n\left(1-\frac{k}{2^{*}}\right)} d y \\
& \quad=C t_{\alpha}^{k(n-2)-n}+o\left(t_{\alpha}^{k(n-2)-n}\right) \\
& \int_{\pi_{-x_{\alpha}}\left(S_{+}^{n}\right)} y^{j} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{k}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{-\frac{k n}{2^{*}}}\left(1+|y|^{2}\right)^{-n\left(1-\frac{k}{2^{*}}\right)} d y \\
& \quad=o\left(t_{\alpha}^{k(n-2)-n-1}\right) \\
& \int_{\pi_{-x_{\alpha}}\left(S_{+}^{n}\right)}|y|^{2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{k}\left(t_{\alpha}^{-2}+|y|^{2}\right)^{-\frac{k n}{2^{*}}}\left(1+|y|^{2}\right)^{-n\left(1-\frac{k}{2^{*}}\right)} d y \\
& \quad=O\left(t_{\alpha}^{k(n-2)-n-2}\right)
\end{aligned}
$$

so that

$$
\pi_{-x_{0}}^{i}\left(x_{\alpha}\right)=o\left(t_{\alpha}^{-1}\right)
$$

This proves (3.1). As in subsection 2.1, we may then take $x_{\alpha}=x_{0}$ in Theorem 0.3 .

We now compute $t_{\alpha}$. For length reasons, we give details in the case $n \geq 6,2 p<n-4$, and leave the proof of Theorem 0.5 to the reader for the other cases. The necessary material will be found in subsections 2.1 and 2.2 , and in Robert [26]. Performing once more the change of variables $x=t_{\alpha} y$, and since one may take $x_{\alpha}=x_{0}$, the different terms in (2.2) are :

$$
I_{\alpha}=\frac{1}{2 t_{\alpha}^{n}} \int_{\mathbb{R}^{n}} \frac{\left(\nabla\left[\left(c_{n} \tilde{S}_{g}-\alpha K_{n}^{-1}\right) \tilde{\varphi}^{2^{*}-2}\right](y), y\right) \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2}}{\left(t_{\alpha}^{-2}+|y|^{2}\right)^{n-2}\left(1+|y|^{2}\right)^{2}} d y
$$

$$
\begin{aligned}
& I I_{\alpha}=t_{\alpha}^{-n} \int_{\mathbb{R}^{n}} \frac{\left(c_{n} \tilde{S}_{g}(y)-\alpha K_{n}^{-1}\right) \tilde{\varphi}(y)^{2^{*}-2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2}}{\left(t_{\alpha}^{-2}+|y|^{2}\right)^{n-2}\left(1+|y|^{2}\right)^{3}} d y \\
& I I I_{\alpha}=t_{\alpha}^{-n} \int_{\mathbb{R}^{n}} \frac{\left(c_{n} \tilde{S}_{g}(y)-\alpha K_{n}^{-1}\right) \tilde{\varphi}(y)^{2^{*}-2}|y|^{2} \tilde{v}_{\alpha}\left(t_{\alpha} y\right)^{2}}{\left(t_{\alpha}^{-2}+|y|^{2}\right)^{n-2}\left(1+|y|^{2}\right)^{3}} d y
\end{aligned}
$$

We first deal with $I_{\alpha}$. We write that

$$
\begin{aligned}
\left(\nabla\left[\left(c_{n} \tilde{S}_{g}-\alpha K_{n}^{-1}\right) \tilde{\varphi}^{2^{*}-2}\right]\left(\frac{x}{t_{\alpha}}\right), x\right)= & c_{n} \varphi\left(x_{0}\right)^{2^{*}-2} \frac{\tilde{S}_{g}^{(2 p)}(0)}{(2 p-1)!} r^{2 p} \\
& +o\left(r^{2 p}\right)+o\left(B_{0}(g)-\alpha\right)
\end{aligned}
$$

so that, with (2.6) and using the assumption $2 p<n-4$,

$$
\begin{aligned}
I_{\alpha}= & \frac{c_{n} \omega_{n}^{-\frac{2}{2^{*}}}}{2} \varphi\left(x_{0}\right)^{2^{*}-2} \frac{\tilde{S}_{g}^{(2 p)}(0)}{(2 p-1)!} t_{\alpha}^{-2 p-4} \int_{\mathbb{R}^{n}}\left(1+|y|^{2}\right)^{2-n}|y|^{2 p} d y \\
& +o\left(t_{\alpha}^{-2 p-4}\right)+o\left(\left(B_{0}(g)-\alpha\right) t_{\alpha}^{-4}\right)
\end{aligned}
$$

For $I I_{\alpha}$ and $I I I_{\alpha}$, we write that

$$
\begin{aligned}
& \left(c_{n} \tilde{S}_{g}(y)-\alpha K_{n}^{-1}\right) \tilde{\varphi}(y)^{2^{*}-2} \\
& =K_{n}^{-1}\left(B_{0}(g)-\alpha\right) \varphi\left(x_{0}\right)^{2^{*}-2}+c_{n} \varphi\left(x_{0}\right)^{2^{*}-2} \frac{\tilde{S}_{g}^{(2 p)}(0)}{(2 p)!} r^{2 p} \\
& \quad+o\left(B_{0}(g)-\alpha\right)+o\left(r^{2 p}\right)
\end{aligned}
$$

This leads to

$$
\begin{aligned}
I I_{\alpha}= & K_{n}^{-1} \omega_{n}^{-\frac{2}{2^{*}}}\left(B_{0}(g)-\alpha\right) \varphi\left(x_{0}\right)^{2^{*}-2} t_{\alpha}^{-4} \int_{\mathbb{R}^{n}}\left(1+|y|^{2}\right)^{2-n} d y \\
& +c_{n} \omega_{n}^{-\frac{2}{2^{*}}} \varphi\left(x_{0}\right)^{2^{*}-2} \frac{\tilde{S}_{g}^{(2 p)}(0)}{(2 p)!} t_{\alpha}^{-4-2 p} \int_{\mathbb{R}^{n}}|y|^{2 p}\left(1+|y|^{2}\right)^{2-n} d y \\
& +o\left(\left(B_{0}(g)-\alpha\right) t_{\alpha}^{-4}\right)+o\left(t_{\alpha}^{-4-2 p}\right)
\end{aligned}
$$

and

$$
I I I_{\alpha}=o\left(\left(B_{0}(g)-\alpha\right) t_{\alpha}^{-4}\right)+o\left(t_{\alpha}^{-4-2 p}\right)
$$

Coming back to (2.2), and passing to the limit $\alpha \rightarrow B_{0}(g)$, we get that

$$
\begin{align*}
& \lim _{\alpha \rightarrow B_{0}(g)}\left(B_{0}(g)-\alpha\right) t_{\alpha}^{2 p} \\
& =\frac{c_{n} K_{n}(p+1)}{(2 p)!} \frac{\int_{\mathbb{R}^{n}}|y|^{2 p}\left(1+|y|^{2}\right)^{2-n} d y}{\int_{\mathbb{R}^{n}}\left(1+|y|^{2}\right)^{2-n} d y}\left(-\tilde{S}_{g}^{(2 p)}(0)\right) \tag{3.2}
\end{align*}
$$

We now compute $\tilde{S}_{g}^{(2 p)}(0)$. For that purpose, let $f \in C^{\infty}\left(\mathbb{R}^{n}\right)$ be radially symmetrical with respect to $x_{0}$ and such that

$$
f^{(k)}(0)=0 \text { for all } 0 \leq k<2 p \text { and } f^{(2 p)}(0) \neq 0
$$

As one easily checks,

$$
\begin{aligned}
& \left(-\Delta_{\xi}\right)^{k} f(0)=0 \quad \text { for any } 0 \leq k<p \\
& \left(-\Delta_{\xi}\right)^{p} f(0)=\frac{n(n+2) \ldots \ldots(n-2+2 p)}{3 \times 5 \times \ldots \ldots \times(2 p-1)} f^{(2 p)}(0)
\end{aligned}
$$

Moreover, thanks to the formula that relates the scalar curvatures of two conformal metrics,

$$
\left(-\Delta_{\xi}\right)^{p} \tilde{S}_{g}(0)=4^{p} \varphi\left(x_{0}\right)^{p\left(2^{*}-2\right)}\left(-\Delta_{g}\right)^{p} S_{g}\left(x_{0}\right)
$$

Hence,

$$
\tilde{S}_{g}^{(2 p)}(0)=2^{2 p} \frac{3 \times 5 \times \ldots \ldots \times(2 p-1)}{n(n+2) \ldots \ldots . .(n-2+2 p)} \varphi\left(x_{0}\right)^{p\left(2^{*}-2\right)}\left(-\Delta_{g}\right)^{p} S_{g}\left(x_{0}\right)
$$

Together with (3.2), this proves the theorem when $n \geq 6$ and $2 p<n-4$. As already mentioned, the proof for the other cases goes in a similar way.

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